



User Manual of LCF20A1-H00

Product Description



Foreword

Dear users,

Thanks for choosing the LCF20A1 (simple-pendulum right-angle) fiber laser automatic focusing cutting head produced by Shenzhen Ospri Intelligent Technology Co., LTD. We do much appreciate your trust in our products.

To help gain an overall understanding on our products, and facilitate your use, we prepare the user manual, which specifies the features, structural characteristics, technical characteristics, operating instructions, maintenance, etc. of the products. Please consult this manual where necessary.

Before using the product, please read this manual carefully to help you use the product more efficiently. For any problem during use, please feel free to call us and we will provide you services wholeheartedly.

Important:

The contents specified in this manual are protected by the *Copyright Law*. Any organization or individual, without the approval of Shenzhen Ospri Intelligent Technology Co., LTD., shall not duplicate or compile this manual by any means or any form.

Please read this manual carefully before using the product, in order to ensure your safety and normal functioning of the product.

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Chapter 1 Overview

1.1 Technical Parameters

① See Table 1.0 for the technical parameters of the product:

Name	Fiber laser cutting head
Model	LCF20A1
Interface type	Q+、QD、LOE3.1、LOE3.2
Applicable wavelength	1,064±10nm
Rated power	≤20KW
Focal length	250mm/300mm
Collimation focal length	100mm
Nozzle model	Various models and specifications
Adjustment range of focus	-50mm~+50mm -70mm~+70mm
Adjustment range of alignment	±1.5mm
Speed of focus adjustment	400mm/s
Repetitive positioning accuracy of focusing axis	0.05mm
A-axis action range	±45°
Rated rotation speed	30r/min
Angular acceleration	240rad/s ²
Positioning accuracy	1arcmin
Auxiliary gas pressure	≤3Mpa
Weight	10KG

Table 1.0

1.2 Precautions

- ① Please wear specialized laser safety goggles to ensure personal safety when the cutting head is used in coordination with laser cutting machine.
- ② Please take preventive measures and operate with caution to prevent burning of cutting head and laser nozzle due to the deviation of laser beam from central axis.
- ③ Keep the cutting head clean and tidy and prevent coolant, condensate or other foreign matter from entering sensor parts; otherwise, it may cause sensor failure.
- ④ When processing products with laser, use protective devices to prevent the laser beam from causing personal injury.

Chapter 2 Structural Characteristics

2.1 Structure

See Figure 1.0 for the brief description of product structure.

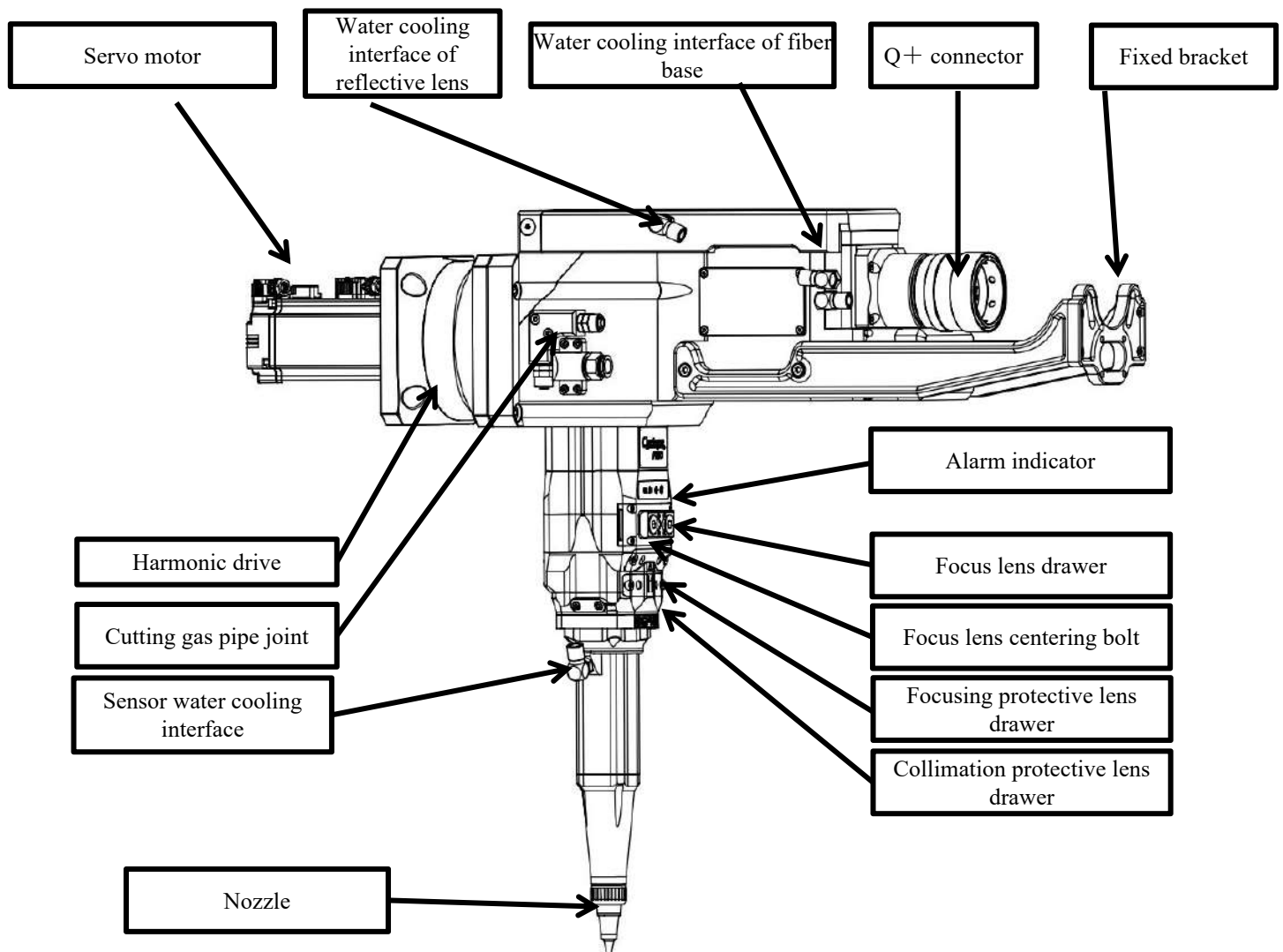


Figure 1.0

See Figure 1.1 for the brief description of product structure.

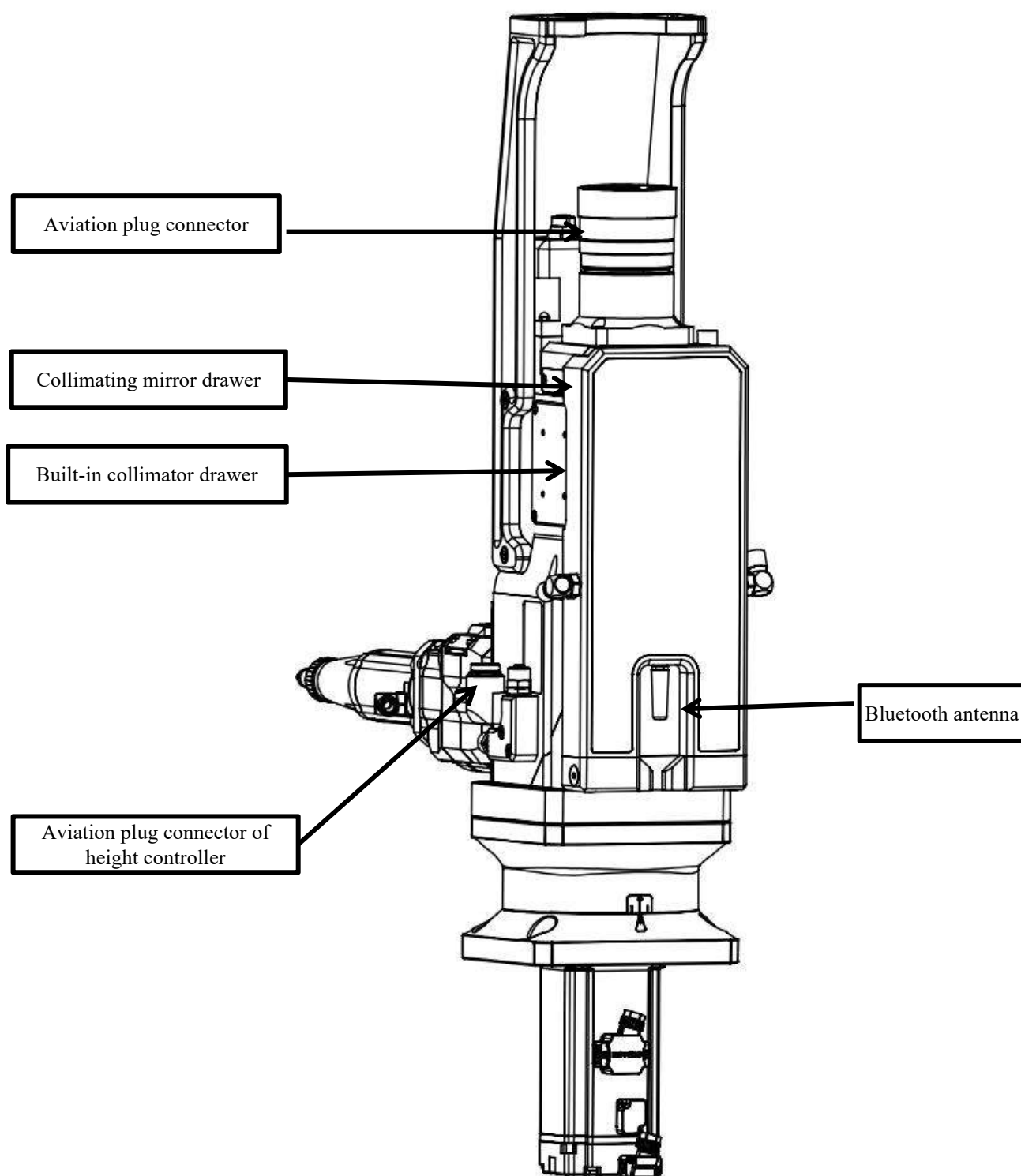


Figure 1.1

2.2 Parts

1. Water cooling interface of fiber base: Mainly used for cooling fiber interface and collimation protective lens.
2. Aviation plug connector: Signal outputs such as power lines for motor, encoder line, limit, etc.
3. Collimation protective lens drawer: When inserting and removing the fiber head, prevent dust from entering the cutting head to protect the collimation lens.
4. Collimation lens drawer: The inserting and removing component for replacing and maintaining collimation lens.
5. Focus lens drawer: Inserting and removing window for replacing and maintaining the focus lens; centering the laser beam spot.
6. Focus protective lens drawer: Protecting the focus lens for fast replacement.
7. Cutting protective lens drawer: Sealing the cutting gas and protecting the focus lens.
8. Cutting gas pipe interface: 10mm gas pipe interface, which is used for inputting gas during cutting.
9. Centering knob: Adjusting the center so that the light beam passes through the center of the nozzle.
10. Aviation plug connector of height controller: The interface for connecting the cutting head and height controller.
11. Alarm light: It is in green during normal working, in yellow for pre-warning and in red for alarming.
12. Harmonic drive: Reduction ratio 100, larger torque
13. Fixed bracket: Used for fixing the fiber.
14. Fiber interface: Compatible to such interfaces as QBH and G5.
15. Bluetooth antenna: Used for enhancing signal, and transmitting to and connecting mobile APP.

2.3 Parts (Lens Size)

See Figure 1.2 for details.

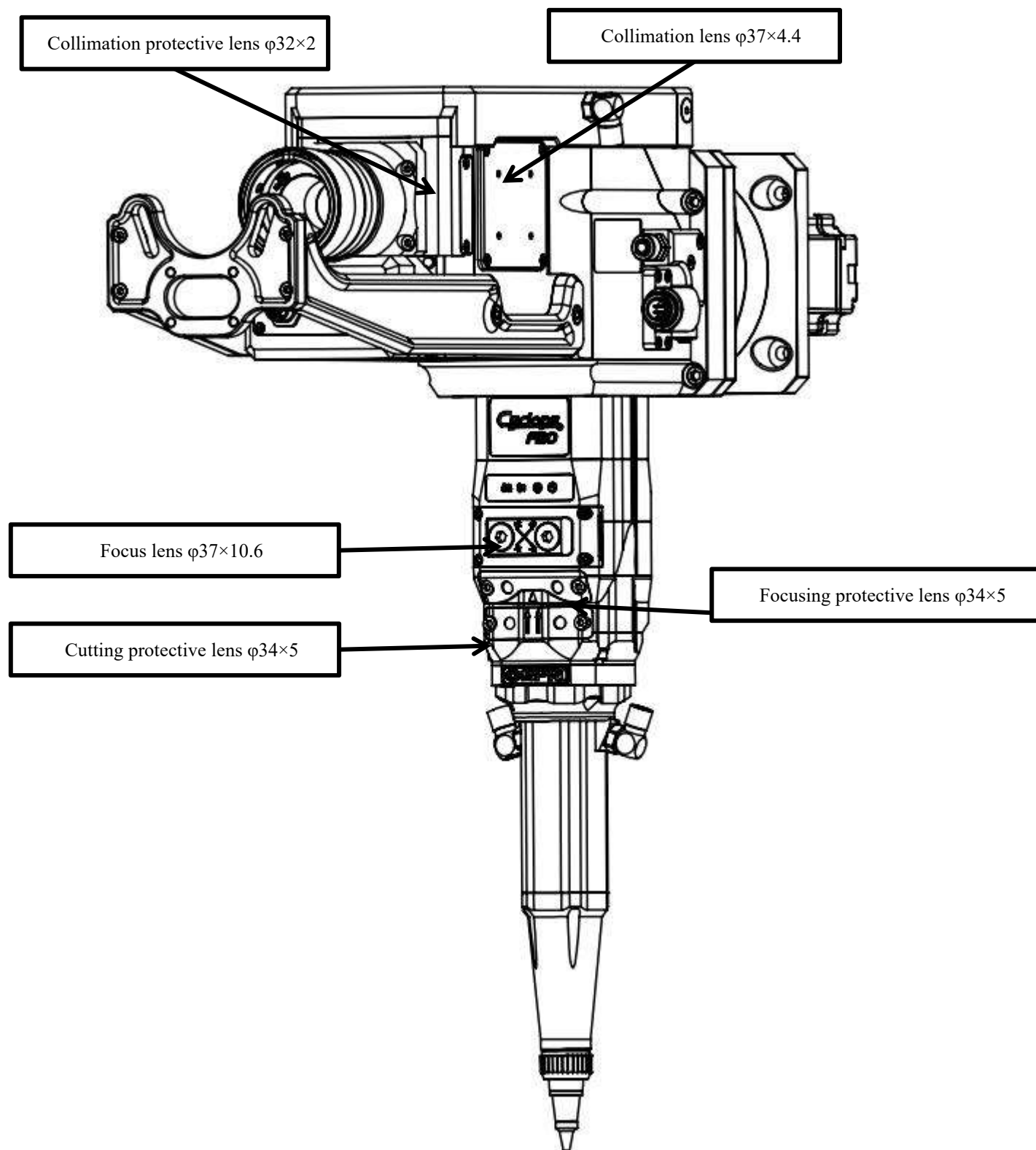


Figure 1.2

Chapter 3 Installation

3.1 Cutting Head Installation

Dimensional drawing of cutting head installation (collimation F100/Focus F300), as shown in Figure 1.3 below.

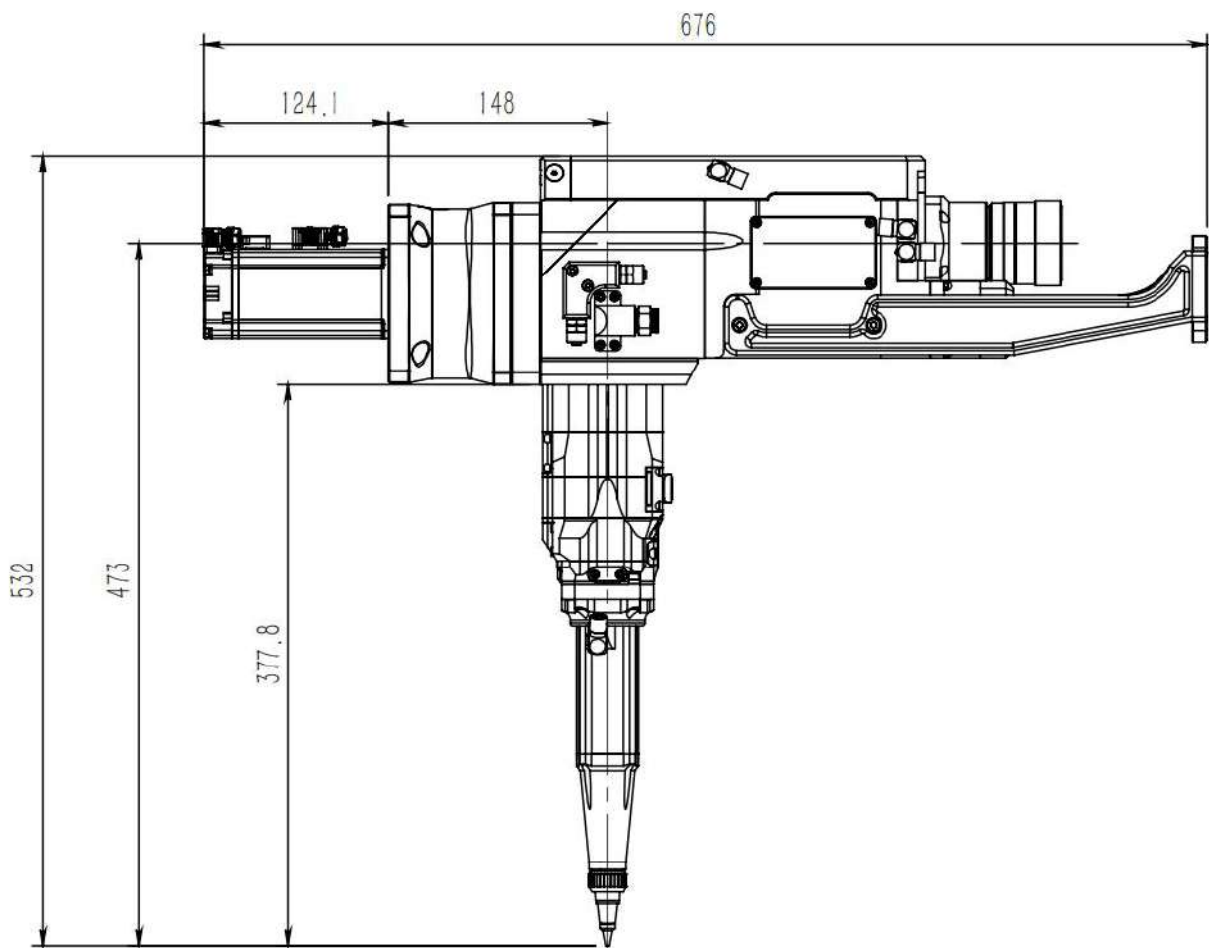


Figure 1.3

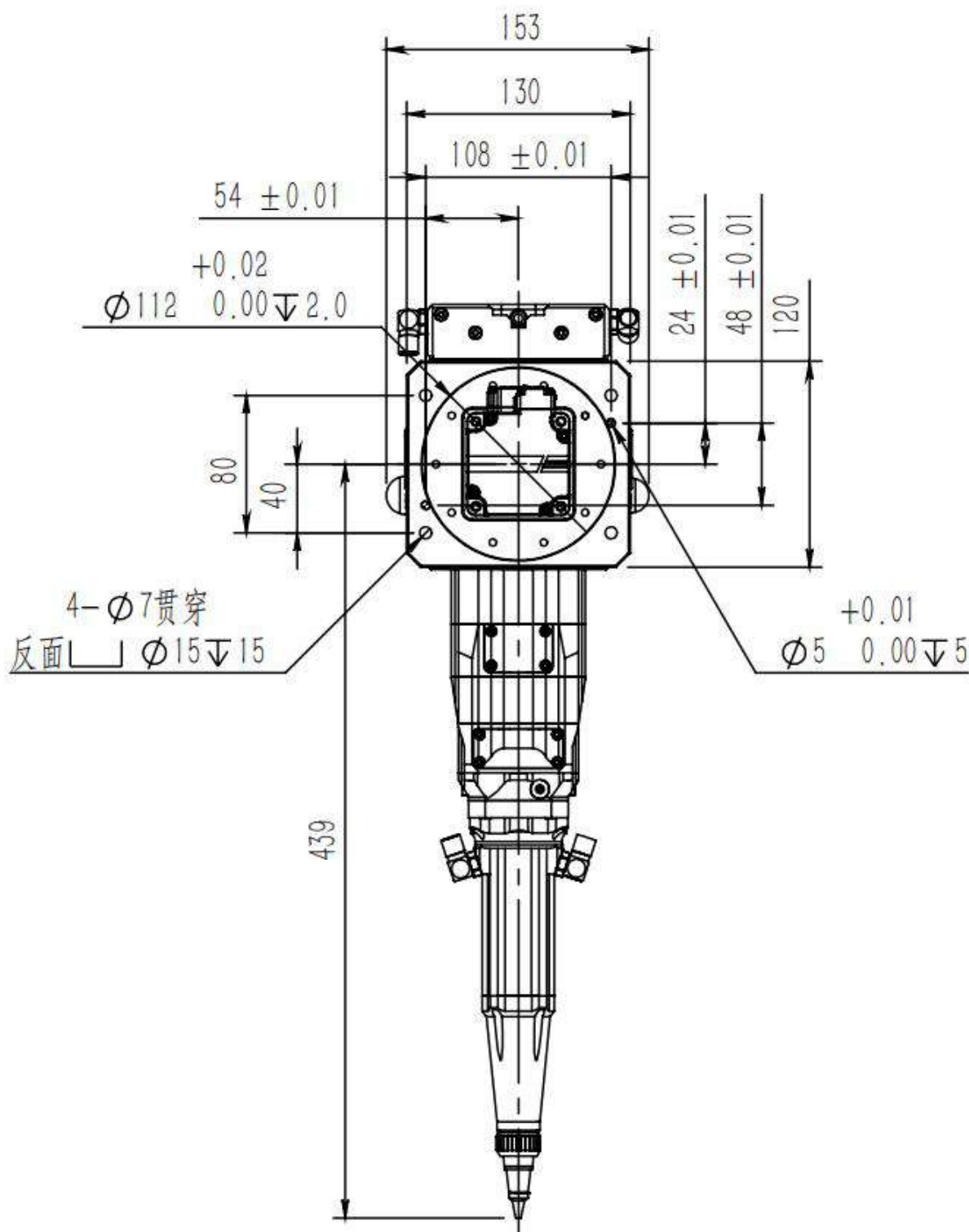


Figure 1.3

3.2 Pipeline Connection

3.2.1 Water Cooling Pipeline.

① Used for cooling the fiber base, collimation protective lens, reflective lens and sensor; 1 inlet and 1 outlet cooling pipes, as shown in Figure 1.4 below.

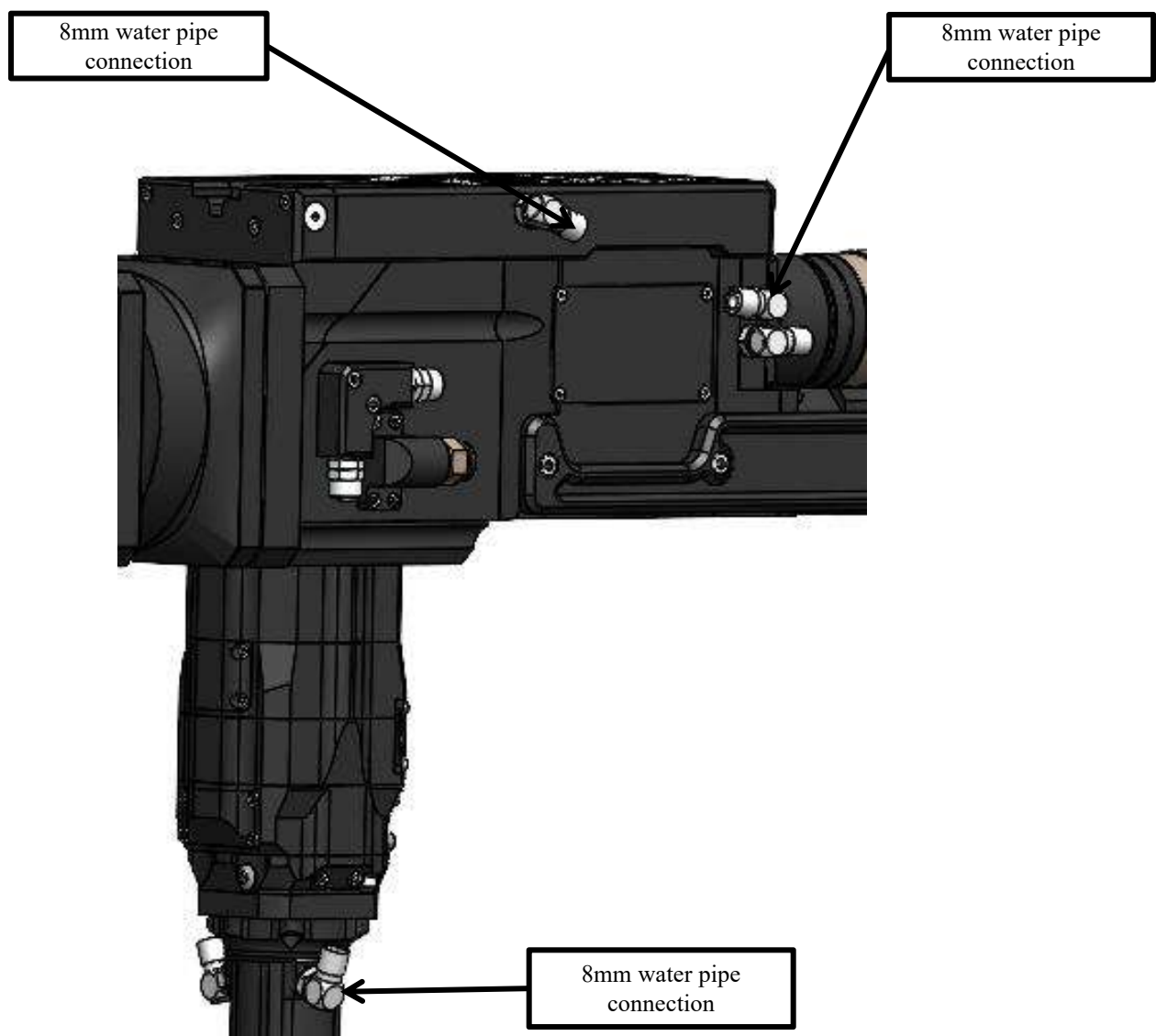


Figure 1.4

3.2.2 Auxiliary Gas Pipeline.

- ① The inlet is connected to a 10mm gas pipe, as shown in Figure 1.5, for docking cutting gas; input pressure $< 3.0\text{Mpa}$.

Variety of conventional gases: Oxygen, nitrogen and compressed air.

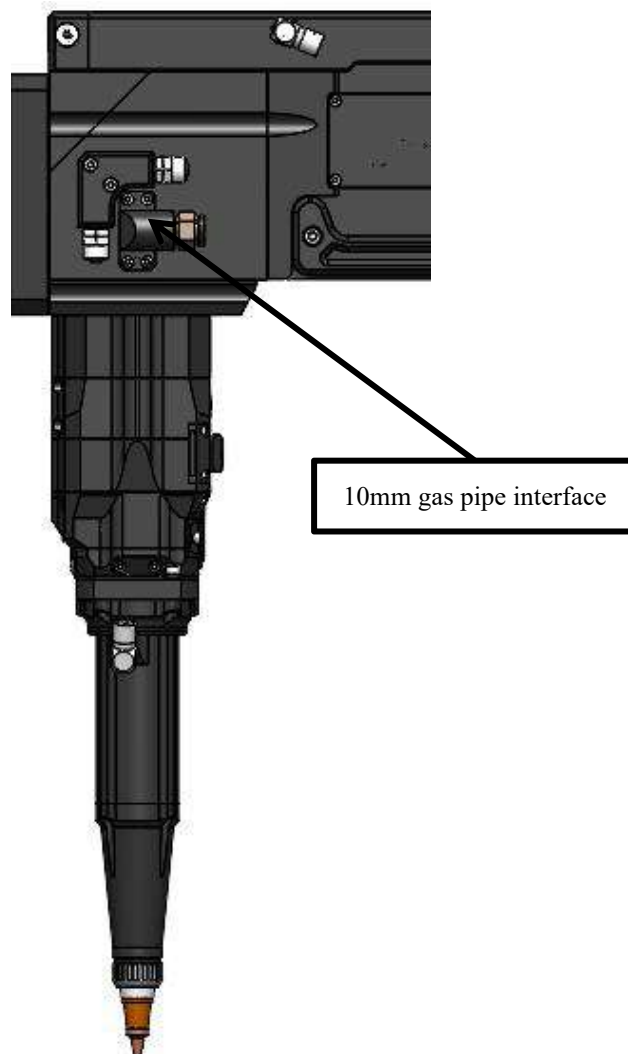


Figure 1.5

Note: The gas entering auxiliary pipelines must be filtered and dried; otherwise, it will contaminate and finally damage the protective lens.

3.3 Wiring Definitions and Requirements

3.3.1 Aviation Plug Interfaces.

- ① Cut off the power supply before inserting or removing the aviation plug; otherwise, the motor may be damaged; while connecting power line and signal line, pay special attention to the position of gap. Avoid damaging the pin. See Figure 1.6 below for details.

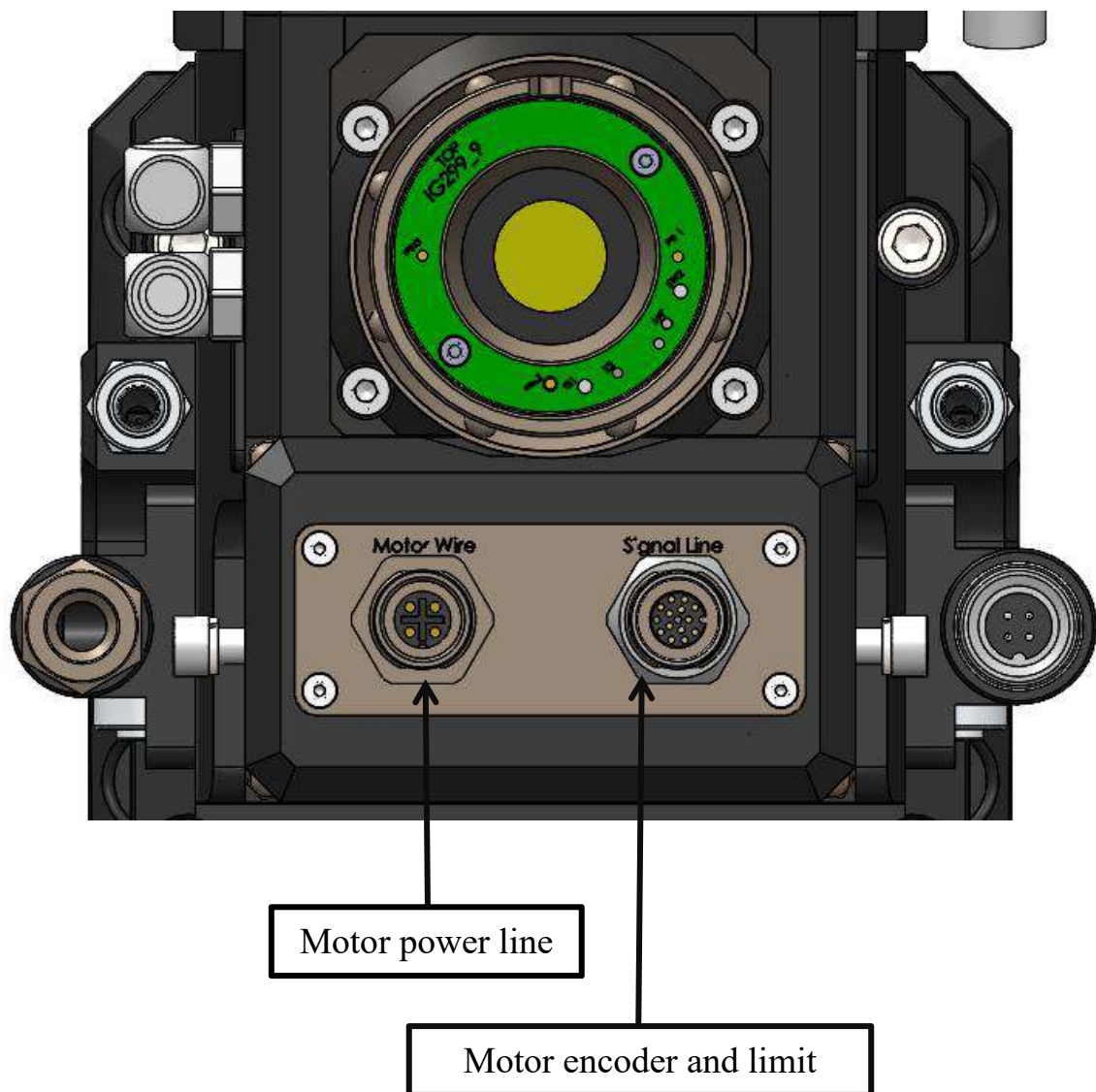
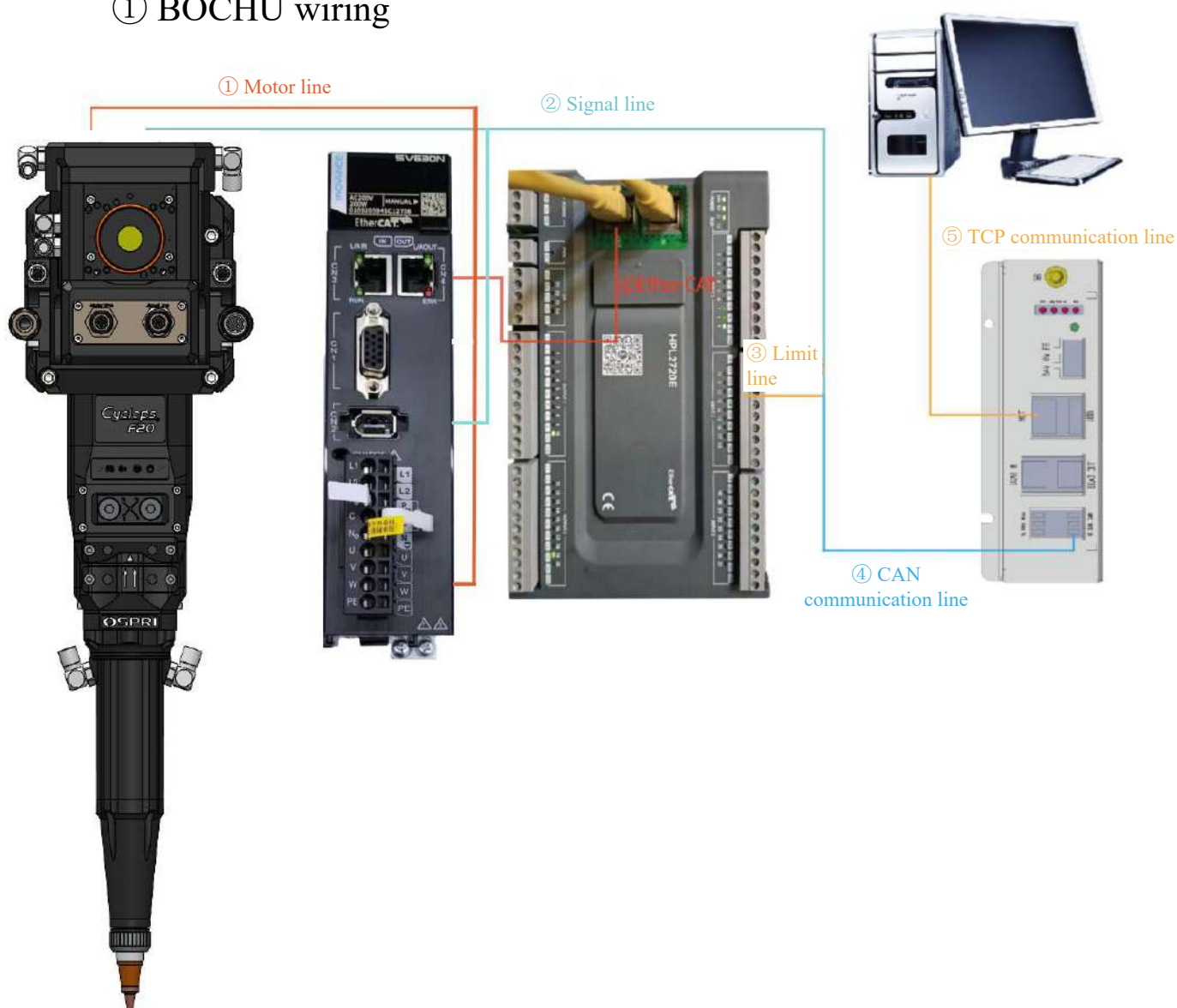


Figure 1.6

3.3.2 BOCHU Wiring Definition

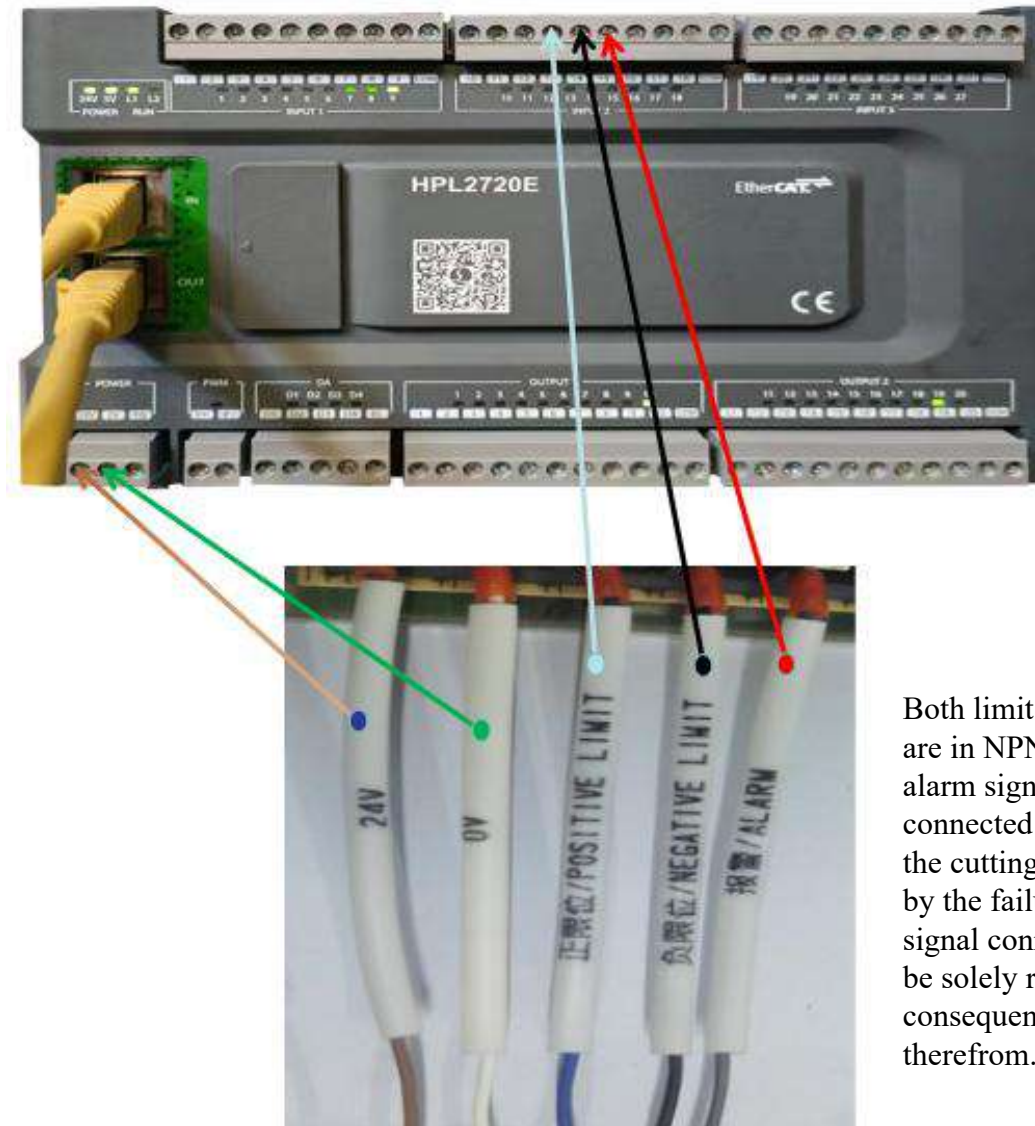
① BOCHU wiring



② Connection of servo driver power supply (single-phase 220V)



③ Signal line and IO wiring



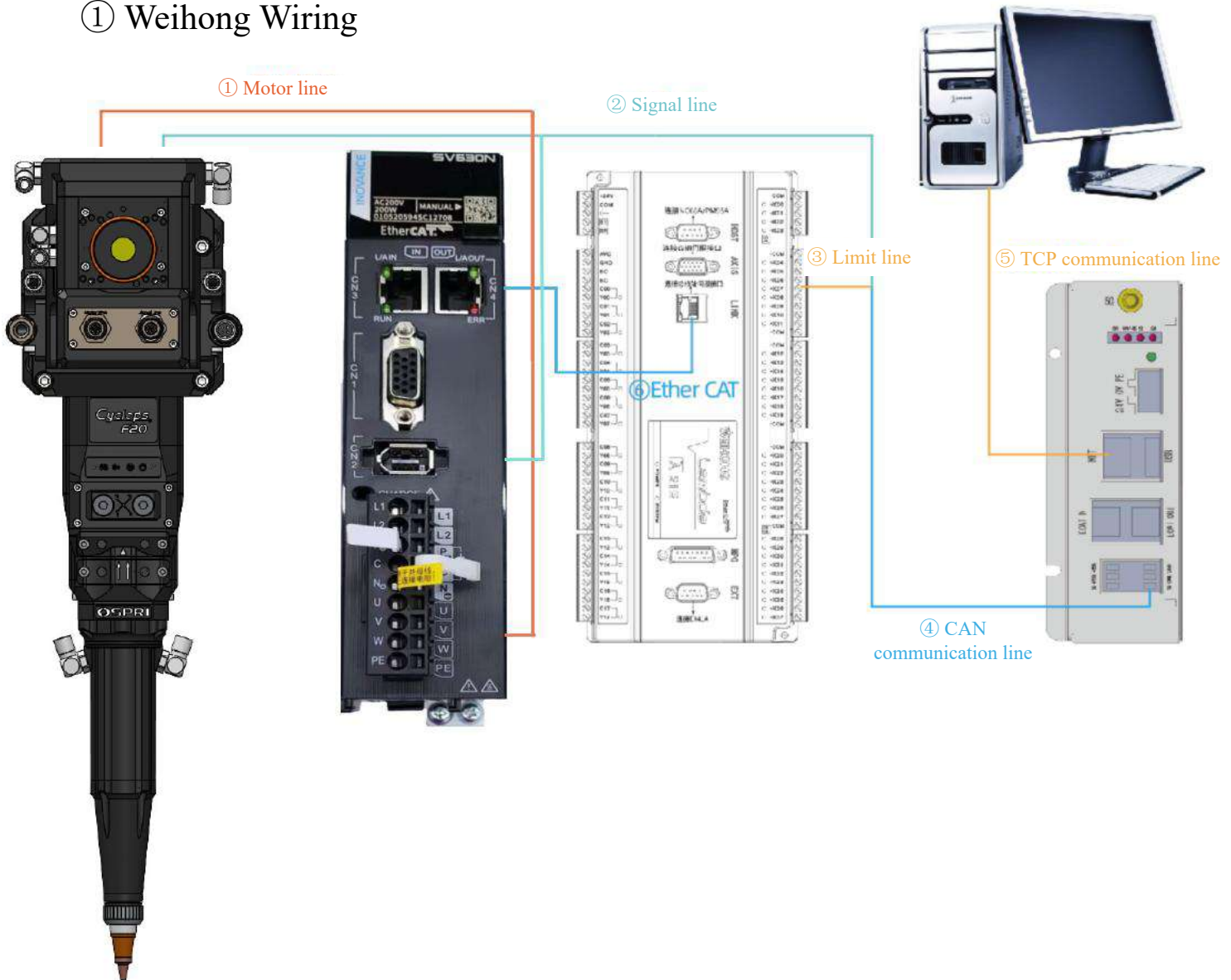
Both limit and alarm signals are in NPN output. The alarm signal must be connected to the system. If the cutting head is damaged by the failure in alarm signal connection, user shall be solely responsible for the consequences arising therefrom.

④ Setting of wiring parameters

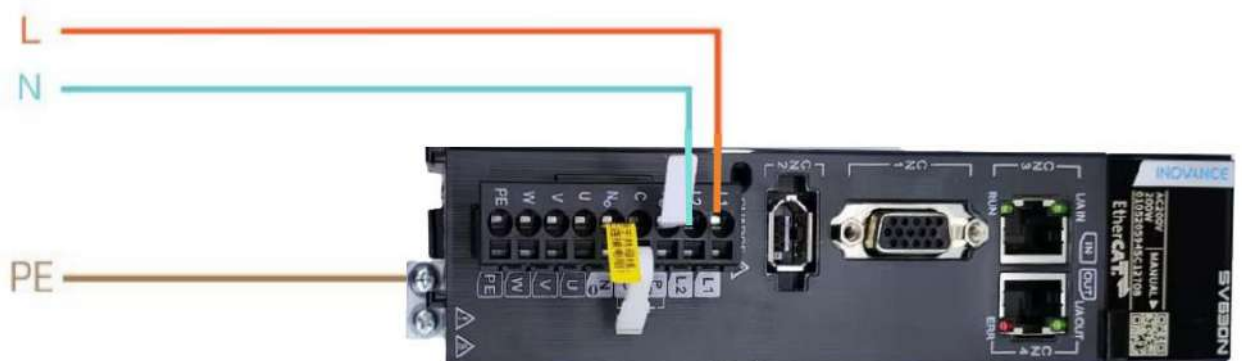
Parameter No.	Parameter value	Parameter content
H0200	9	Control mode
H0202	1	Rotation direction
H0900	1	Self-adjusting mode
H0901	18	Rigidity grade
H0507	262144	Numerator of electronic gear ratio
H0509	10000	Denominator of electronic gear ratio
H0E31	2	Synchronization mode

3.3.3 Weihong Wiring Definition

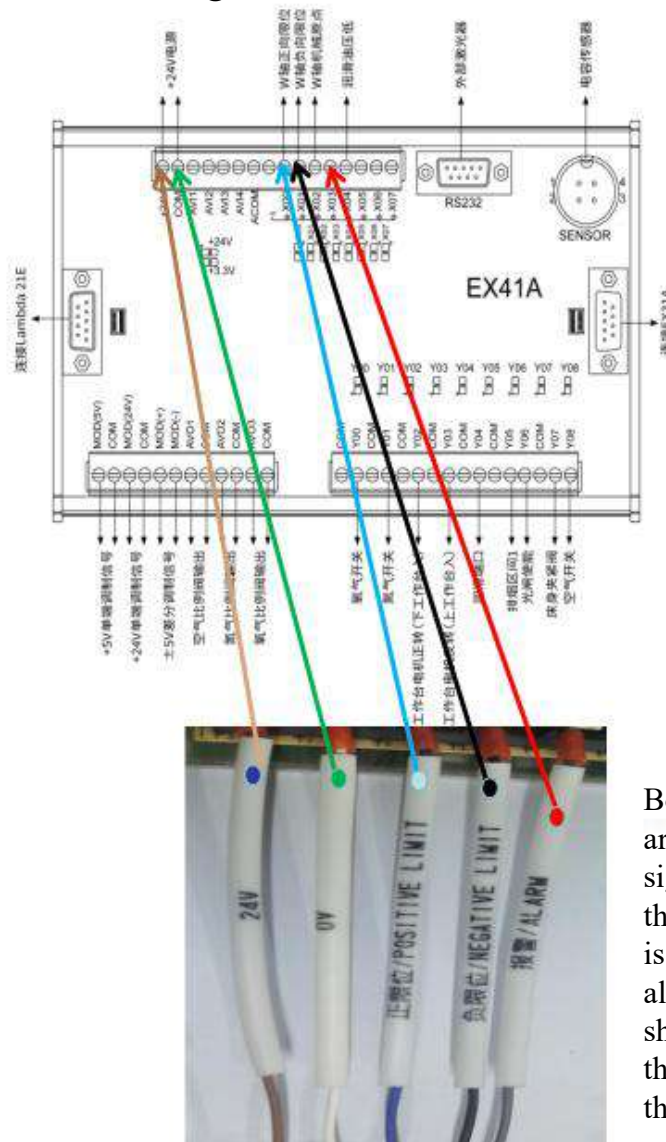
① Weihong Wiring



② Connection of servo driver power supply (single-phase 220V)



③ Signal line and IO wiring



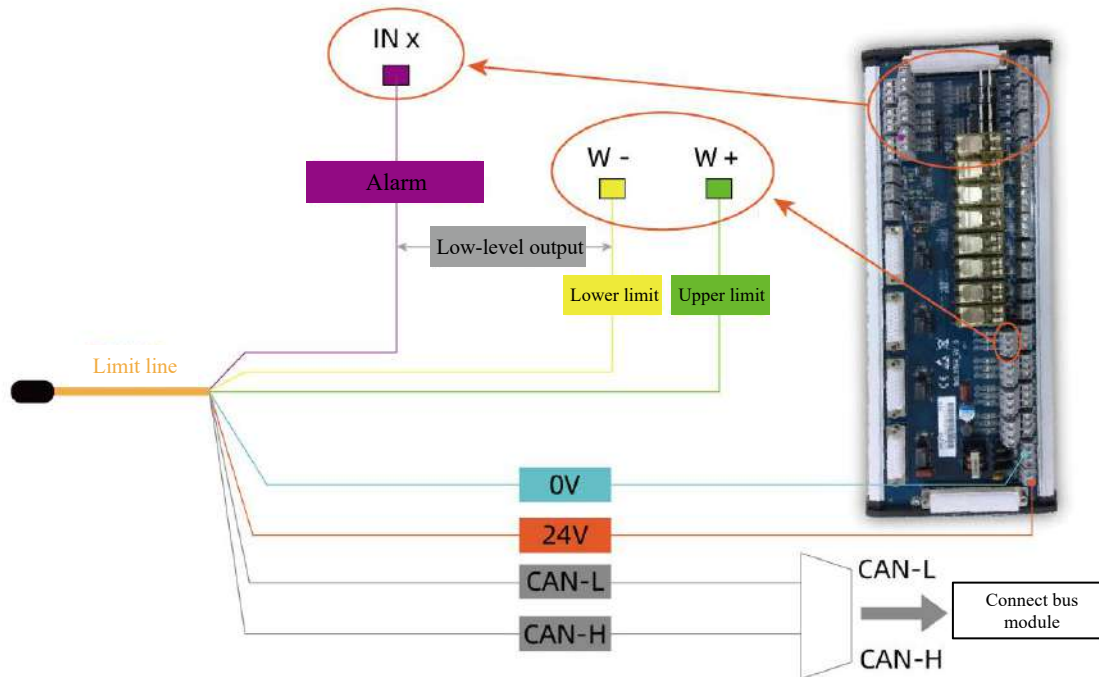
Both limit and alarm signals are in NPN output. The alarm signal must be connected to the system. If the cutting head is damaged by the failure in alarm signal connection, user shall be solely responsible for the consequences arising therefrom.

④ Setting of wiring parameters

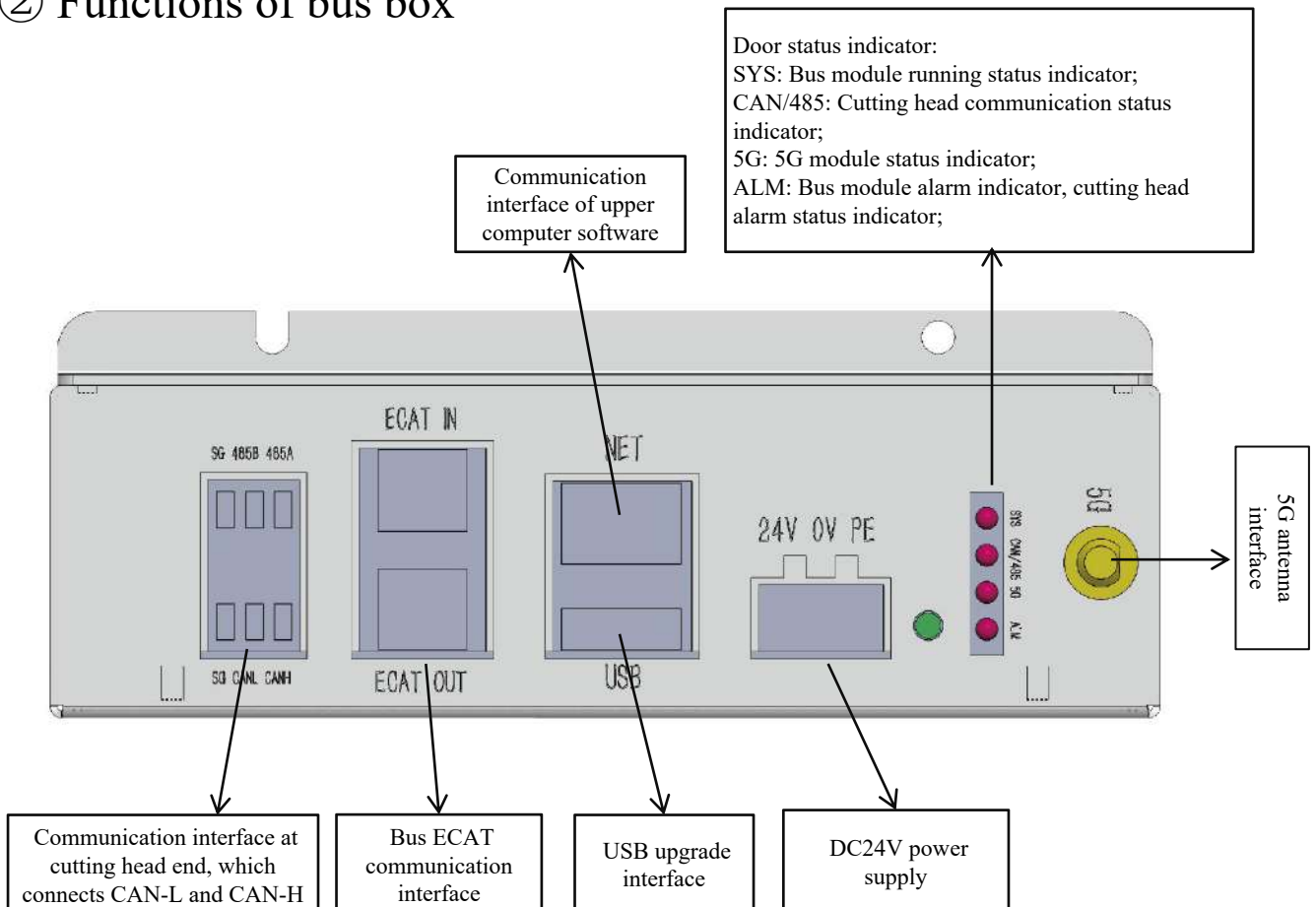
Parameter No.	Parameter value	Parameter content
H0200	9	Control mode
H0202	1	Rotation direction
H0900	1	Self-adjusting mode
H0901	18	Rigidity grade
H0507	262144	Numerator of electronic gear ratio
H0509	10000	Denominator of electronic gear ratio
H0E31	2	Synchronization mode

3.3.4 Wiring Instructions of Bus Box

① Connection of signal line CAN bus



② Functions of bus box



3.4 QBH Fiber Laser Head Installation

- ① Place the cutting head horizontally, remove the dust cover, and tear off the dust sticker; As shown in Figure 2.1 below

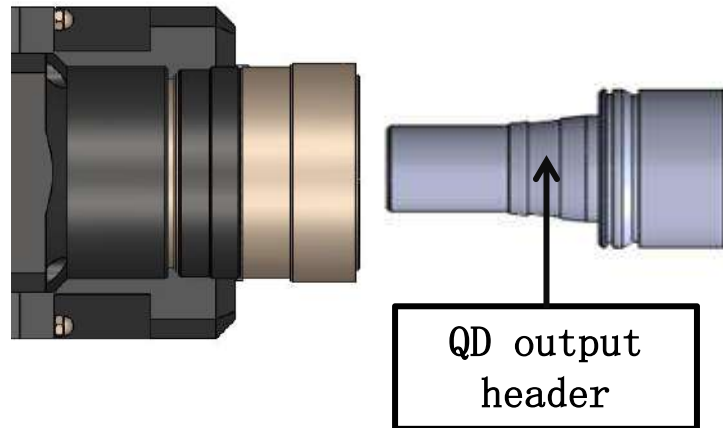


Figure 2.1

- ② Correspond the QD output head of the laser to the pin slot position. As shown in Figure 2.2 below:

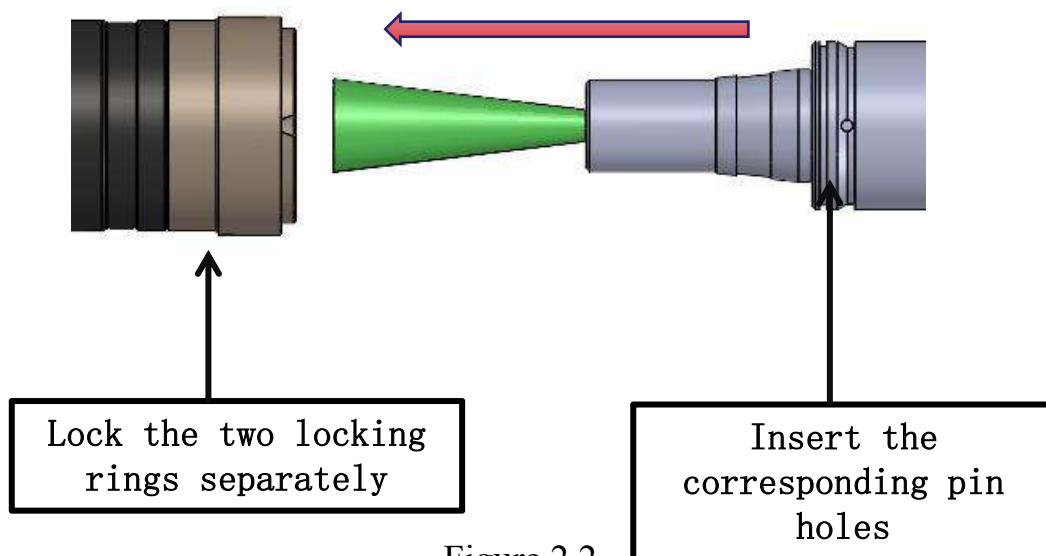


Figure 2.2

Attention: If the fiber head is attached with the original dust-proof gasket, users can choose whether to install dust-proof cover or not during installation.

3.5 Mobile APP Operation Instructions

3.5.1 Install mobile APP software.

- ① After installation, the icon shown in Figure 2.3 will appear; continue by clicking "Install"; the icon shown in Figure 2.4 will appear after installation. This APP currently only supports installation on Android devices.

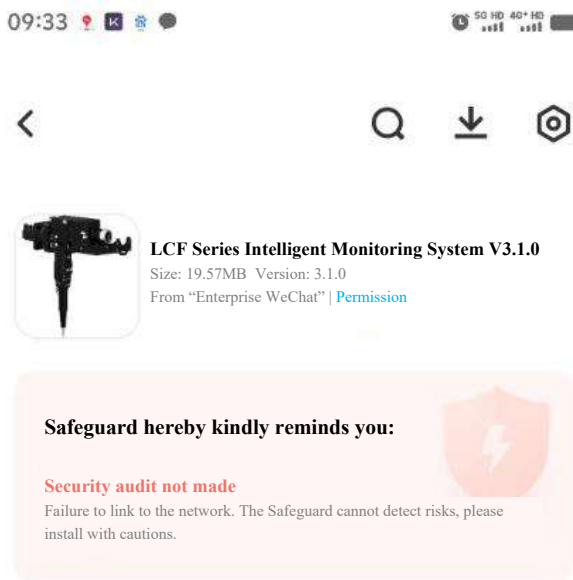


Figure 2.4

Icon display after installation

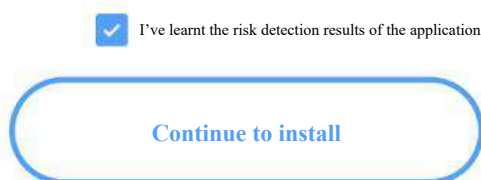


Figure 2.3

3.5.2 APP Software Connection.



Figure 2.5

- ① Click the Bluetooth icon to open the Bluetooth connection interface, as shown in Figure 2.5

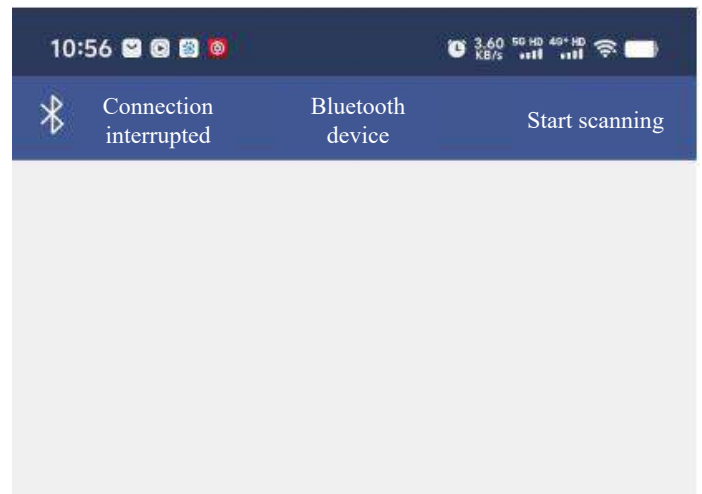


Figure 2.6

- ② Start scanning; if nothing is displayed, click it for more times, as shown in Figure 2.6

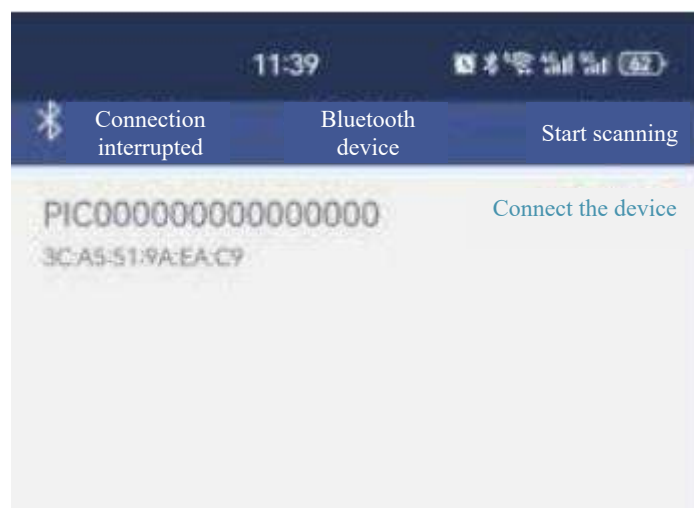


Figure 2.7

- ③ After finding the device through scanning, choose the device to be connected and click [Connect the Device] button and the mobile end will communicate with the device in real time, as shown in Figure 2.7

3.5.3 Software Introduction.

- ① After running LCF APP application, the color of progress bar on the main interface will change based on the actual temperature value detected, as shown in Figure 2.8 Green: The lens temperature is normal according to the monitoring results and can be used normally. Yellow: The lens temperature is too high; check if the lens are polluted. Red: The lens temperature is extremely high and cannot be used continuously. Shut down the device for check.

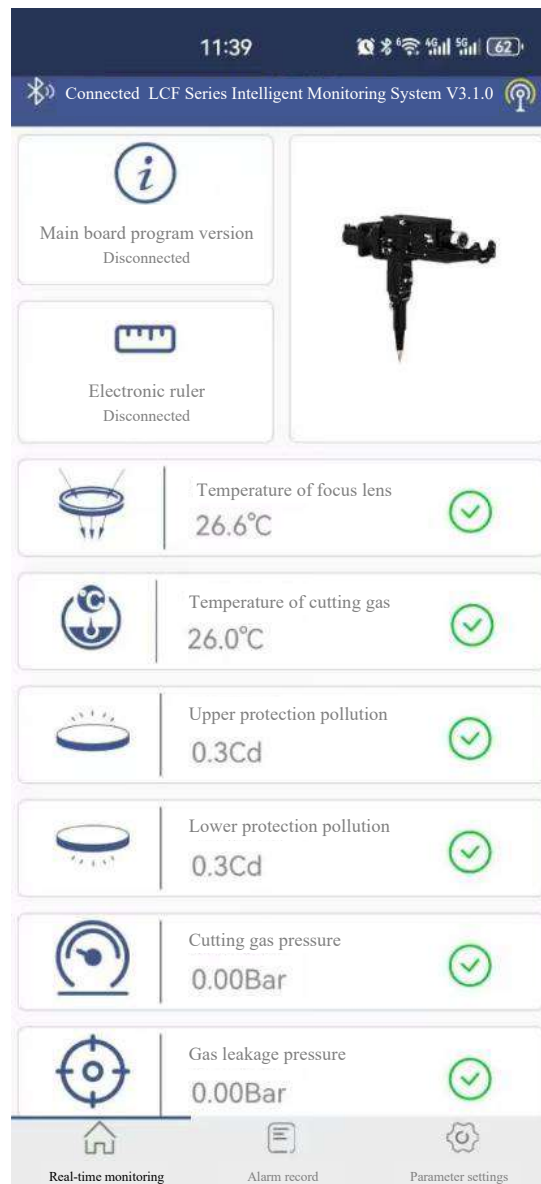
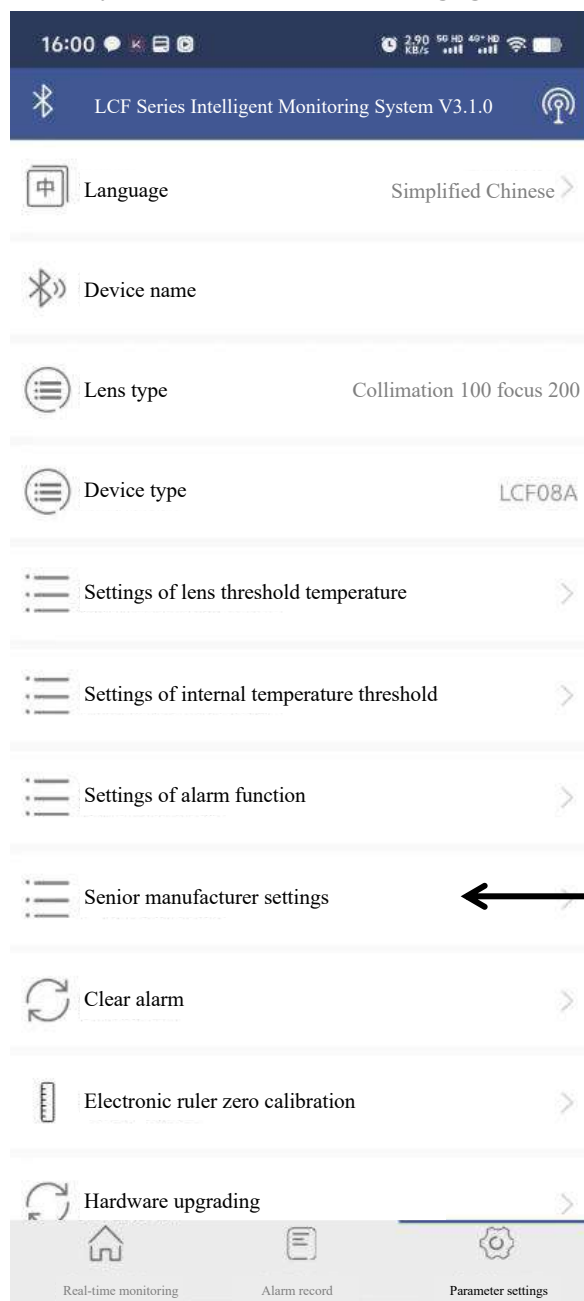


Figure 2.8

3.5.4 Settings of Temperature Parameters

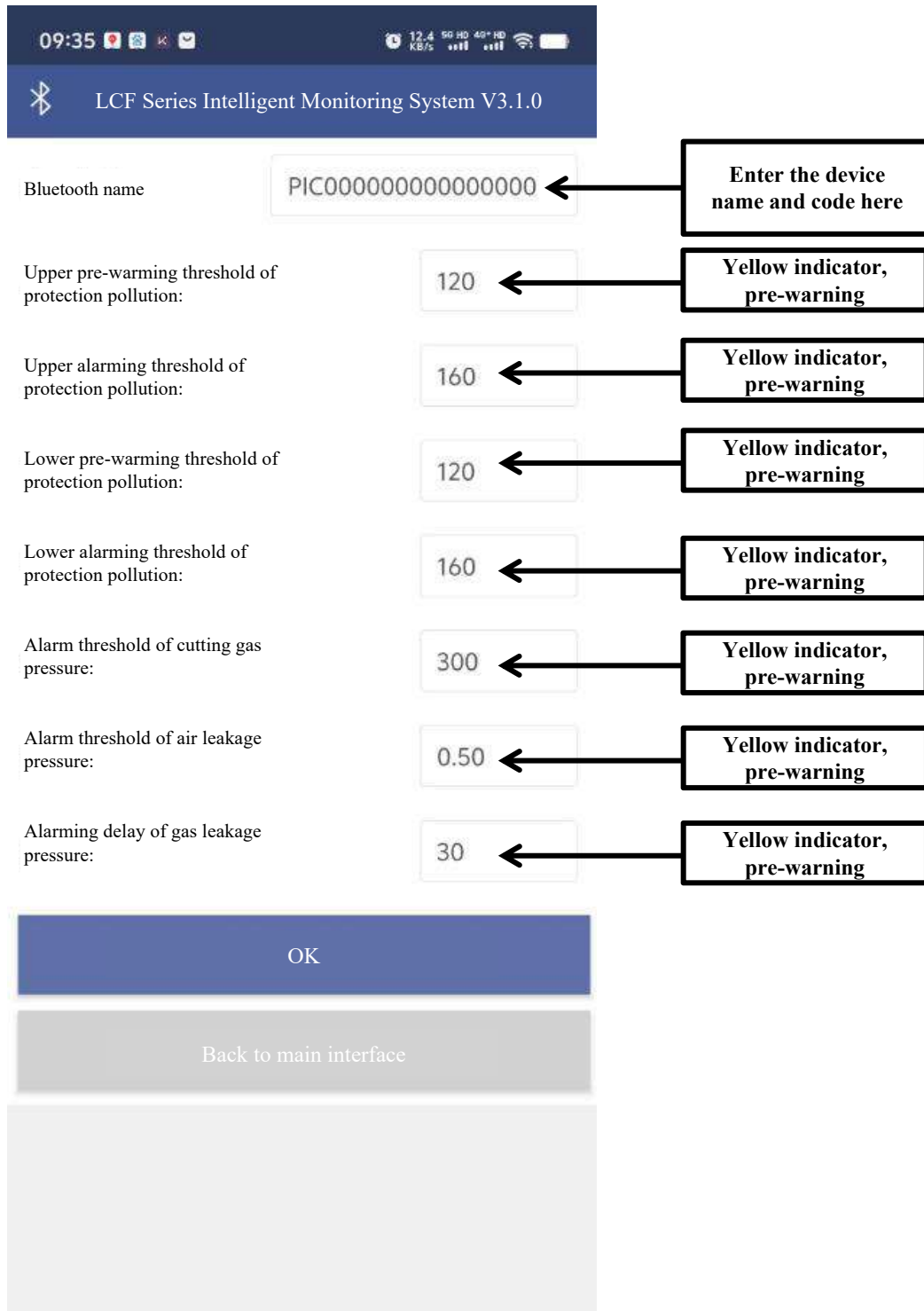
- ① This APP software supports temperature setting function. Different threshold values can be set based on the specific application scenarios. Click the manufacturer settings option and enter the password 85225225 to enter the temperature setting interface, as shown in Figure 2.9.
- ② The software can also monitor the real-time dimensions of the electronic scale, internal temperature and humidity of the cavity, cutting gas pressure, and detect any leaks in the cutting gas.



Click on the manufacturer settings option and enter the password: 85225225

Figure 2.9

- ② On the temperature setting interface, set temperature according to the realities. The pre-warning value must be lower than the alarm value. Click "OK" button after finishing setting This window can also be used for setting the cutting head encoding; when the Bluetooth mode is disconnected, it will automatically switch to the 5G model state, as shown in Figure 3.0



The screenshot shows the 'LCF Series Intelligent Monitoring System V3.1.0' interface. At the top, the status bar displays the time 09:35, battery level at 12.4%, and network status (5G HD, 4G+ HD). The main interface has a blue header with a Bluetooth icon and the system name. Below the header, there are several input fields for settings, each with an annotation box pointing to it:

- Bluetooth name:** The input field contains 'PIC0000000000000000'. An annotation box points to it with the text 'Enter the device name and code here'.
- Upper pre-warning threshold of protection pollution:** The input field contains '120'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Upper alarming threshold of protection pollution:** The input field contains '160'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Lower pre-warning threshold of protection pollution:** The input field contains '120'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Lower alarming threshold of protection pollution:** The input field contains '160'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Alarm threshold of cutting gas pressure:** The input field contains '300'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Alarm threshold of air leakage pressure:** The input field contains '0.50'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.
- Alarming delay of gas leakage pressure:** The input field contains '30'. An annotation box points to it with the text 'Yellow indicator, pre-warning'.

At the bottom of the interface, there are two buttons: a blue 'OK' button and a grey 'Back to main interface' button.

Figure3.0

Chapter 4 Debugging

4.1 Focusing

Focus reset - After powering up the machine, the fourth axis should reset first to bring the focus to the zero position. The figure below shows the cutting head platform parameter configuration for collimation 100/focus 300:



Figure 3.1

① Open the software configuration platform and set the focus retreat distance as 70mm (slightly adjusted based on realities) to make the collimation focus at the zero position (by taking BOCHU as an example), as shown in Figure 3.1

Note: The retreat distance can be adjusted slightly based on the actual cutting focus.

4.1.1 LCF20A1 BOCHU Platform Configuration

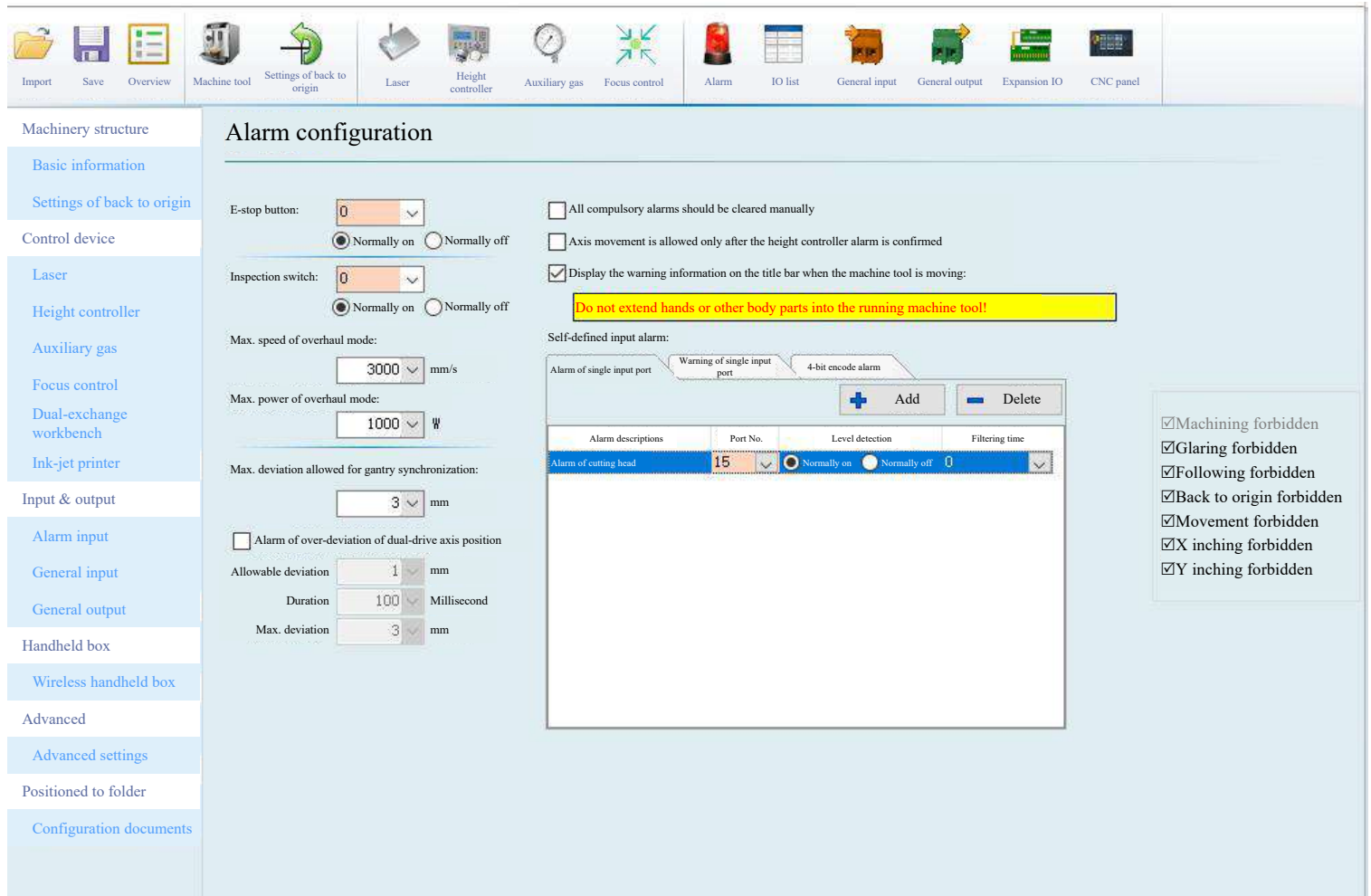
100Collimation250Focus:

Max. adjustment range of focus: -50mm~50mm;
Screw lead: 12.5mm;
Number of pulses per cycle: 10000;
Positive limit: A13;
Negative limit: A14;
Limit logic: Normally on;
Back to origin direction: Positive;
Retreat distance: 50mm;

100 collimation 300 focus:

Max. adjustment range of focus: -70mm~70mm;
Screw lead: 18mm;
Number of pulses per cycle: 10000;
Positive limit: A13;
Negative limit: A14;
Limit logic: Normally on;
Back to origin direction: Positive;
Retreat distance: 70mm;

4.1.2 Configuration of Alarm Signal



Alarm configuration

E-stop button: ☐ Normally on ☐ Normally off

Inspection switch: ☐ Normally on ☐ Normally off

Max. speed of overhaul mode: mm/s

Max. power of overhaul mode: W

Max. deviation allowed for gantry synchronization: mm

☐ Alarm of over-deviation of dual-drive axis position

Allowable deviation: mm

Duration: Millisecond

Max. deviation: mm

☐ All compulsory alarms should be cleared manually

☐ Axis movement is allowed only after the height controller alarm is confirmed

☒ Display the warning information on the title bar when the machine tool is moving:

Do not extend hands or other body parts into the running machine tool!

Self-defined input alarm:

Alarm descriptions	Port No.	Level detection	Filtering time
Alarm of cutting head	15	☒ Normally on ☐ Normally off	0

☒ Machining forbidden

☒ Glaring forbidden

☒ Following forbidden

☒ Back to origin forbidden

☒ Movement forbidden

☒ X inching forbidden

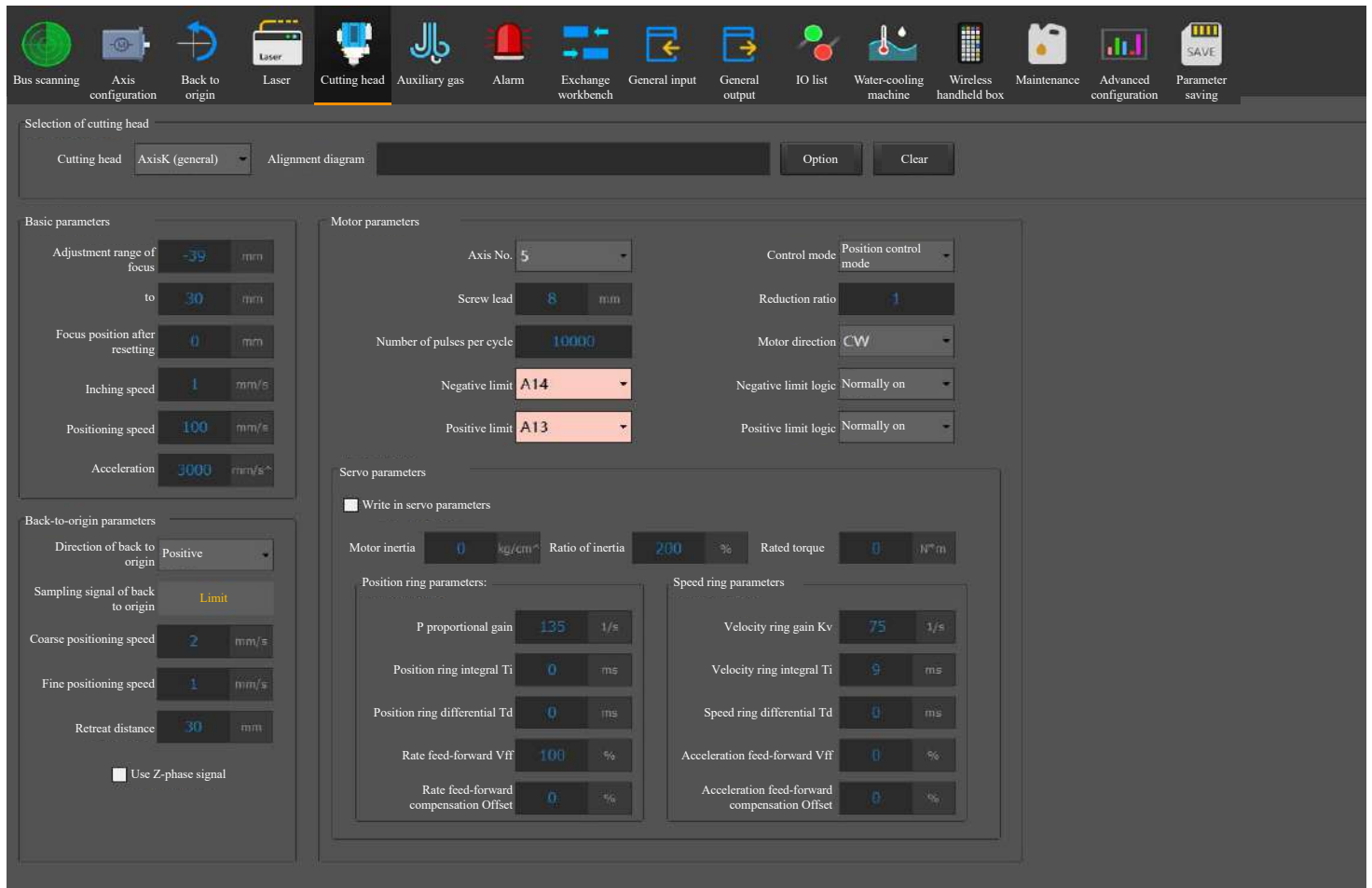
☒ Y inching forbidden

Figure 3.2

Set the input port IN15 as the cutting head alarm signal and logic as normally on. Connect the self-defined port of IO to the corresponding input port, as shown in Figure 3.2.

4.2 FSCUT8000 System Configuration (Bus System)

4.2.1 Configuration of Focus Control and Limit, as shown in Figure 3.3.



The screenshot displays the 'Cutting head' configuration window in the FSCUT8000 software. The interface is organized into several sections:

- Top Navigation Bar:** Contains icons for various system functions: Bus scanning, Axis configuration, Back to origin, Laser, Cutting head (selected), Auxiliary gas, Alarm, Exchange workbench, General input, General output, IO list, Water-cooling machine, Wireless handheld box, Maintenance, Advanced configuration, and Parameter saving.
- Selection of cutting head:** A dropdown menu shows 'AxisK (general)' selected. An 'Alignment diagram' button is also present.
- Basic parameters:**
 - Adjustment range of focus: -39 mm to 30 mm
 - Focus position after resetting: 0 mm
 - Inching speed: 1 mm/s
 - Positioning speed: 100 mm/s
 - Acceleration: 3000 mm/s²
- Back-to-origin parameters:**
 - Direction of back to origin: Positive
 - Sampling signal of back to origin: Limit
 - Coarse positioning speed: 2 mm/s
 - Fine positioning speed: 1 mm/s
 - Retreat distance: 30 mm
 - ☐ Use Z-phase signal
- Motor parameters:**
 - Axis No.: 5
 - Screw lead: 8 mm
 - Number of pulses per cycle: 10000
 - Negative limit: A14
 - Positive limit: A13
 - Control mode: Position control mode
 - Reduction ratio: 1
 - Motor direction: CW
 - Negative limit logic: Normally on
 - Positive limit logic: Normally on
- Servo parameters:**
 - ☐ Write in servo parameters
 - Motor inertia: 0 kg/cm²
 - Ratio of inertia: 200 %
 - Rated torque: 0 N·m
- Position ring parameters:**
 - P proportional gain: 135 1/s
 - Position ring integral Ti: 0 ms
 - Position ring differential Td: 0 ms
 - Rate feed-forward Vff: 100 %
 - Rate feed-forward compensation Offset: 0 %
- Speed ring parameters:**
 - Velocity ring gain Kv: 75 1/s
 - Velocity ring integral Ti: 9 ms
 - Speed ring differential Td: 0 ms
 - Acceleration feed-forward Vff: 0 %
 - Acceleration feed-forward compensation Offset: 0 %

Figure 3.3

LCF20A1 BOCHU Platform Configuration

100Collimation250Focus:

Max. adjustment range of focus: -50mm~50mm;

Screw lead: 12.5mm;

Number of pulses per cycle: 10000;

Positive limit: A13;

Negative limit: A14;

Limit logic: Normally on;

Back to origin direction: Positive;

Retreat distance: 50mm;

100 collimation 300 focus:

Max. adjustment range of focus: -70mm~70mm;

Screw lead: 18mm;

Number of pulses per cycle: 10000;

Positive limit: A13;

Negative limit: A14;

Limit logic: Normally on;

Back to origin direction: Positive;

Retreat distance: 70mm;

4.2.2 Configuration of Alarm Signal

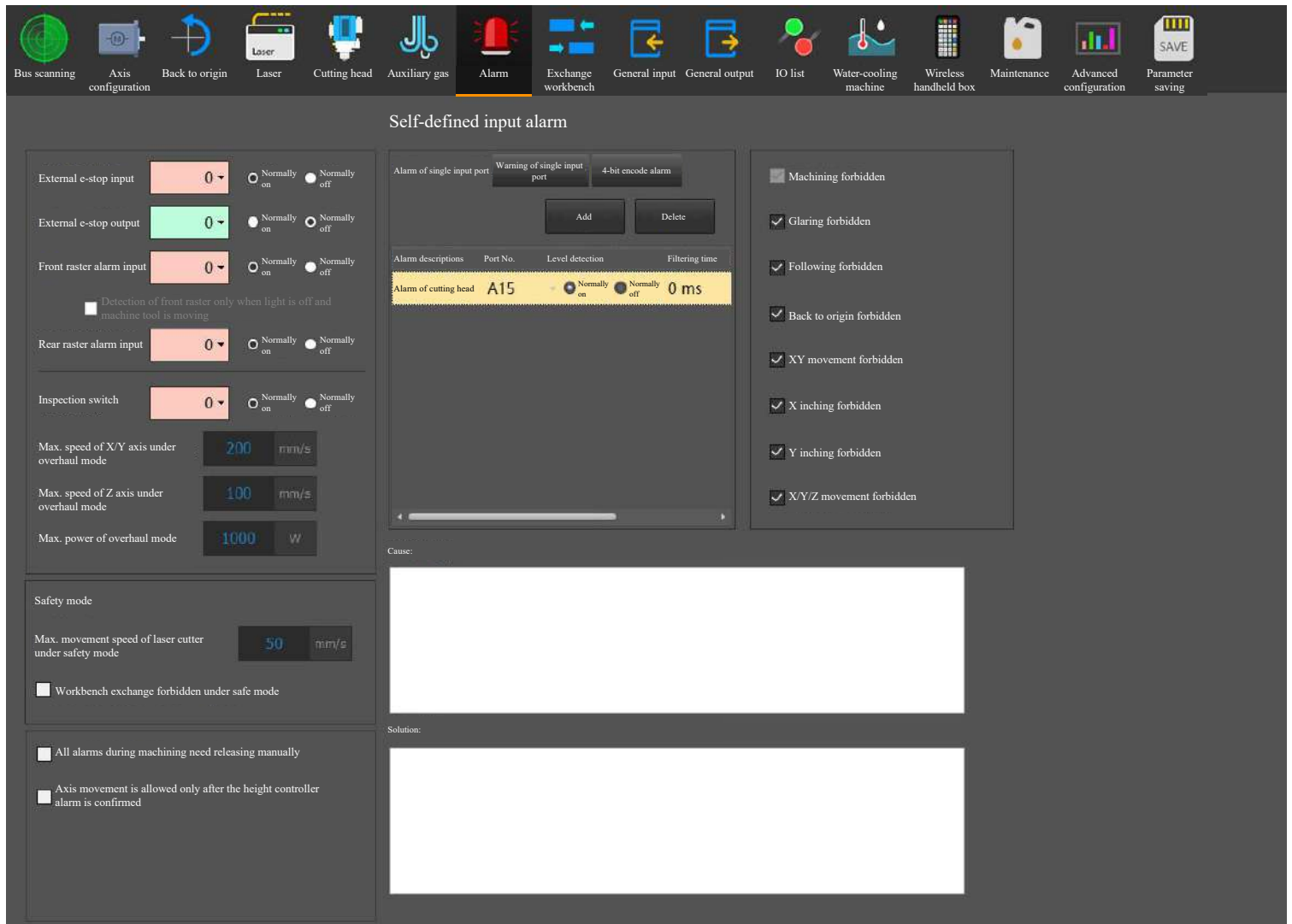


Figure 3.4

Set the input port IN15 as the cutting head alarm signal and logic as normally on. Connect the self-defined port of IO to the corresponding input port, as shown in Figure 3.4.

4.3 Configuration of LS6000M Bus System

4.3.1 Configuration of W-axis Parameters, as shown in Figure 3.8.

常用参数	系统参数	驱动器设置	随动控制	激光器设置	机床维护定期提醒
参数总览	搜索	名称	值	单位	生效时间
机床基本参数		1.0.3 W轴参数			
1.0 轴参数设置		驱动器站地址1(W)	5		重启生效
1.0.0 X轴参数		驱动器站地址2(W)	15		重启生效
1.0.1 Y轴参数		从站地址内轴偏移地址(W)	0		重启生效
1.0.2 Z轴参数		轴方向(W)	1		立即生效
1.0.3 W轴参数		丝杠螺距(W)	8	mm	立即生效
1.1 回原点设置		编码器位数(W)	13		立即生效
1.2 误差补偿设置		编码器类型(W)	0		重启生效
速度及精度控制		电子齿轮比分子(W)	8192		立即生效
外部设备控制		电子齿轮比分母(W)	10000		立即生效
高级功能参数		软限位上限值(W)	30	mm	立即生效
		软限位下限值(W)	-30	mm	立即生效
		启用软限位保护(W)	是		立即生效
		轴最大速度(W)	6000	mm/min	立即生效
		检查轴编码器误差(W)	否		立即生效
		编码器静态公差(W)	0.1	mm	立即生效
		编码器动态公差(W)	40	mm	立即生效

Figure 3.8

LCF20A1 Weihong Platform Configuration

100Collimation250Focus:

Address of driver slave1 (W) : 5;

Address of driver slave2 (W) : 15;

Axis direction: 1;

Screw pitch: 12.5;

Number of encoder bits: 18;

Encoder type: 0;

Numerator of electronic gear ratio (W) : 262144;

Denominator of electronic gear ratio (W) : 10000;

Retreat distance: 50;

Upper limit of soft limit (W) : 50;

Lower limit of soft limit (W) : -50;

Enabling soft limit protection (W) : Yes;

Max. speed of axis (W) : 6000mm/min;

100 collimation 300 focus:

Address of driver slave1 (W) : 5;

Address of driver slave2 (W) : 15;

Axis direction: 1;

Screw pitch: 18;

Number of encoder bits: 18;

Encoder type: 0;

Numerator of electronic gear ratio (W) : 262144;

Denominator of electronic gear ratio (W) : 10000;

Retreat distance: 70;

Upper limit of soft limit (W): 70;

Lower limit of soft limit (W): -70;

Enabling soft limit protection (W) : Yes;

Max. speed of axis (W) : 6000mm/min;

Focus control of LCF20A1 Weihong Platform Configuration

100Collimation250Focus:

Z-phase signal used or not: No;
Coarse positioning direction: 1;
Coarse positioning speed: 600mm/min;
Fine positioning speed: 60mm/min;
Coarse positioning direction: 1;
Retreat distance: 50;
Retreat speed: 200mm/min;

100 collimation 300 focus:

Z-phase signal used or not: No;
Coarse positioning direction: 1;
Coarse positioning speed: 600mm/min;
Fine positioning speed: 60mm/min;
Coarse positioning direction: 1;
Retreat distance: 70;
Retreat speed: 200mm/min;

4.3.2 Correlation of W-axis Alarm Signal

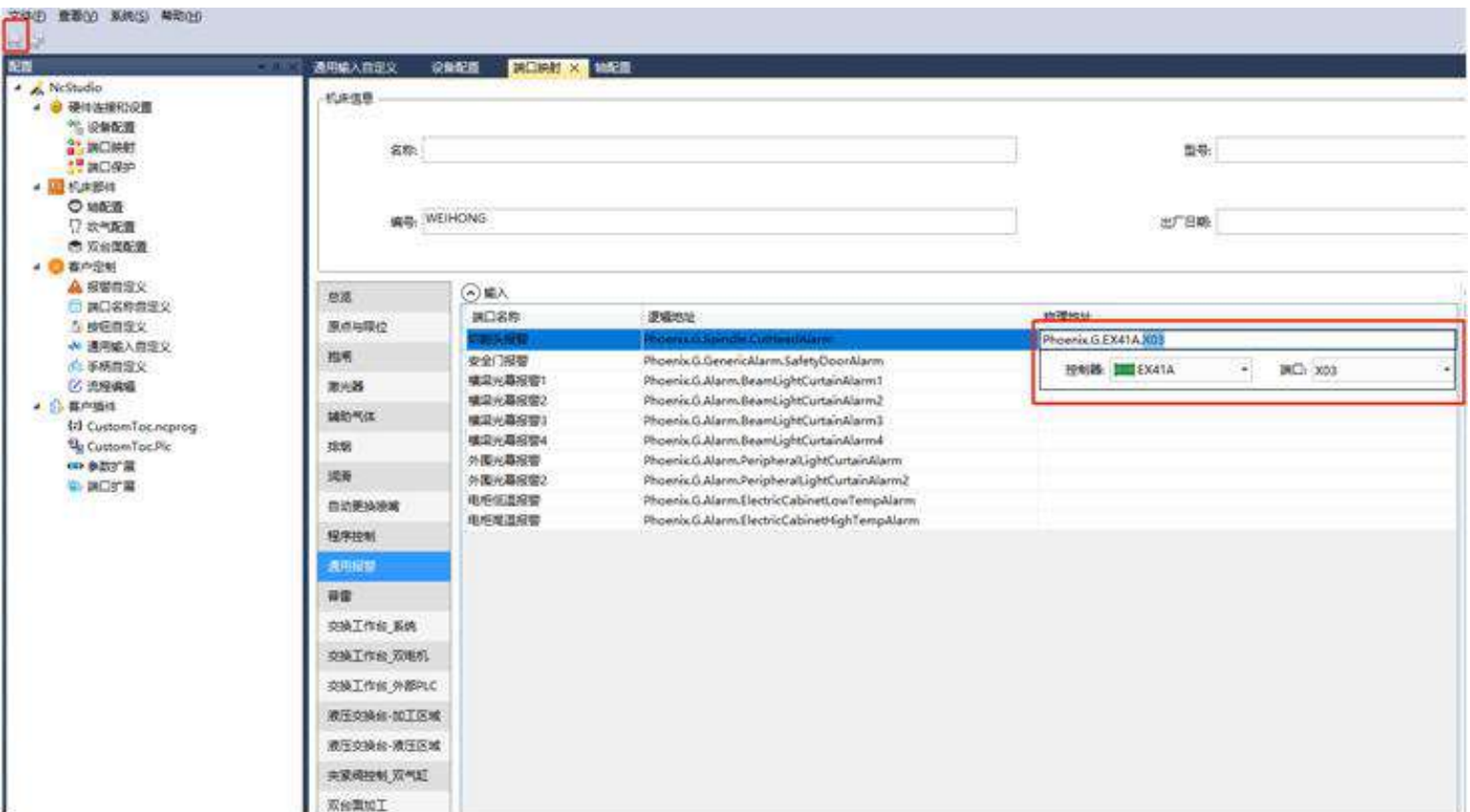


Figure 3.9

General alarm column. Select cutting head alarm and associate the address. Select controller. By taking EX41A as an example, choose Port X03 and connect the self-defined port of IO to the corresponding input port, as shown in Figure 3.9.

外部设备

端口设置

日志列表

地址	极性	采样	描述
LD21E-04.Fln6	NO	S:1ms	随动出错中
LD21E-04.Fln7	NO	S:1ms	浮头标定中
LD21E-04.Fln8	NO	S:1ms	未随动标定
LD21E-04.Fln9	NO	S:1ms	蛙跳中
LD21E-04.Fln10	NO	S:1ms	蛙跳指令出错
LD21E-04.Fln11	NO	S:1ms	碰板
LD21E-04.Fln12	NO	S:1ms	随动到位
LD21E-04.Fln13	NO	S:1ms	随动下限位
LD21E-04.Fln14	NO	S:1ms	电容突变
LD21E-04.Fln15	NO	S:1ms	出边下扎过深
LD21E-04.Fln16	NO	S:1ms	随动上限位
LD21E-04.Fln18	NO	S:1ms	已到达板面位置
LD21E-04.Fln19	NO	S:1ms	喷漆底部或侧面接近板材
EX41A.X00	NO	S:4ms	W轴正向限位
EX41A.X01	NO	S:4ms	W轴负向限位
EX41A.X02	NO	S:4ms	W轴机械原点
EX41A.X03	NO	S:4ms	切割头报警
EX41A.X04	NO	S:4ms	润滑油压低
EX41A.SX07	NO	S:1ms	时间翻转异常
EX31A.X00	NO	S:4ms	交换工作台
EX31A.X01	NO	S:4ms	释放床身
EX31A.X02	NO	S:4ms	床身已释放
EX31A.X05	NO	S:4ms	交换台锁定
EX31A.X06	NC	S:4ms	防护门上到位
EX31A.X07	NO	S:4ms	Z轴负向限位 (上)
EX31A.X08	NO	S:4ms	下工作台入
EX31A.X09	NO	S:4ms	上工作台入
输出端口			
LD21E-04.Axis0_On			X轴伺服使能
LD21E-04.Axis1_On			Y轴伺服使能
LD21E-04.Axis2_On			Z轴伺服使能/Z轴使能
LD21E-04.Axis3_On			Y2轴伺服使能

测试开

测试关

取消测试

取消全部

滤波

修改极性

Figure 4.0

EX41A.X00	NO(normally on)	W-axis positive limit
EX41A.X01	NO(normally on)	W-axis negative limit
EX41A.X03	NO(normally on)	cutting head alarm

4.4 Instructions for Focusing Adjustment

- ① The laser beam must be kept in the center of the nozzle to achieve good joint-cutting effect. When it deviates from the center of the nozzle, make adjustment through the beam centering module, as shown in Figure 4.1 below.

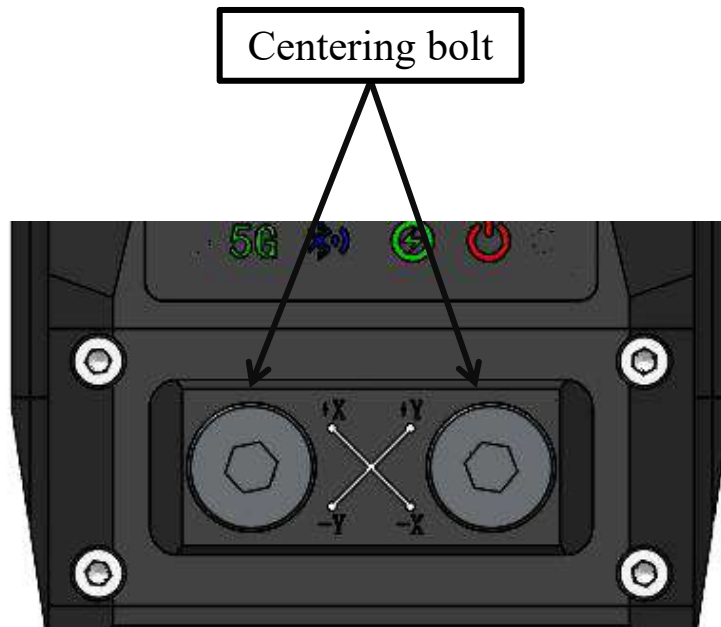


Figure 4.1

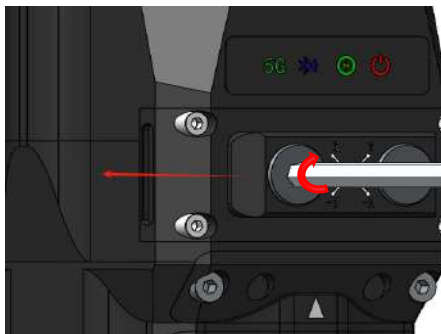


Figure 4.2

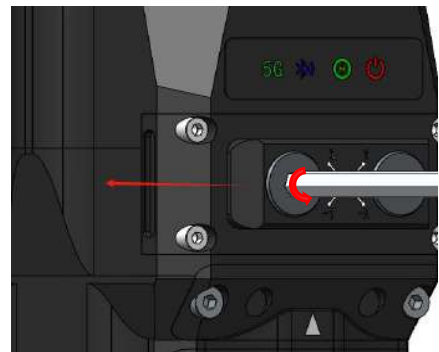


Figure 4.3

Note: When the centering bolt rotates clockwise, the center direction of the lens is shown in Figure 4.2.
When the centering bolt rotates counterclockwise, the center direction of the lens is shown in Figure 4.3.

Chapter 5 Maintenance

5.1 Maintenance and Replacement of Protective Lens

If the cutting effect is poor but the cutting protective lens is normal and burning points are detected on the ceramic piece, the collimation protective lens or focus protective lens possibly is polluted or damaged. In this condition, the after-sales service personnel should check if there is any burning point on the lens. Before checking, use a clean cloth dampened with alcohol to wipe the exterior surface

5.1.1 Disassembly of collimation protective lens, as shown in Figures 4.1 and 4.2 below.

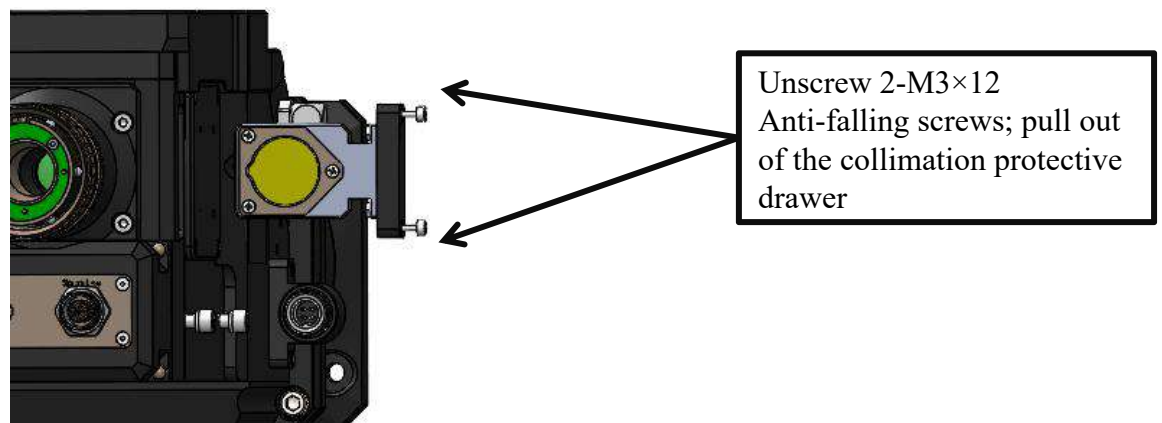


Figure 4.1

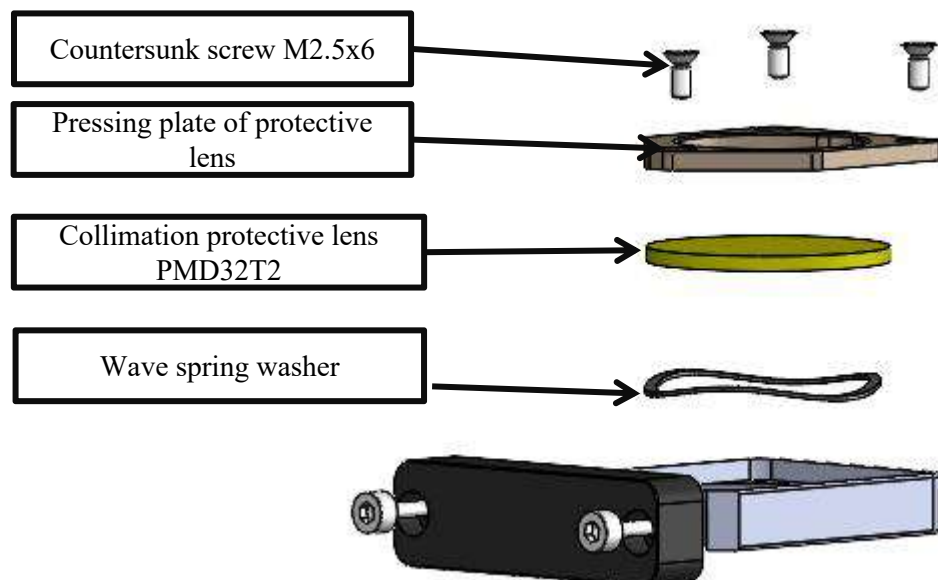


Figure 4.2

5.1.2 Disassembly and Assembly of Focusing Protective Lens

Loosen the two M4×16 hexagon socket anti-falling screws, pull out the protective lens drawer, and replace the protective lens (PMD34T5), as shown in Figures 4.4 and 4.5 below.

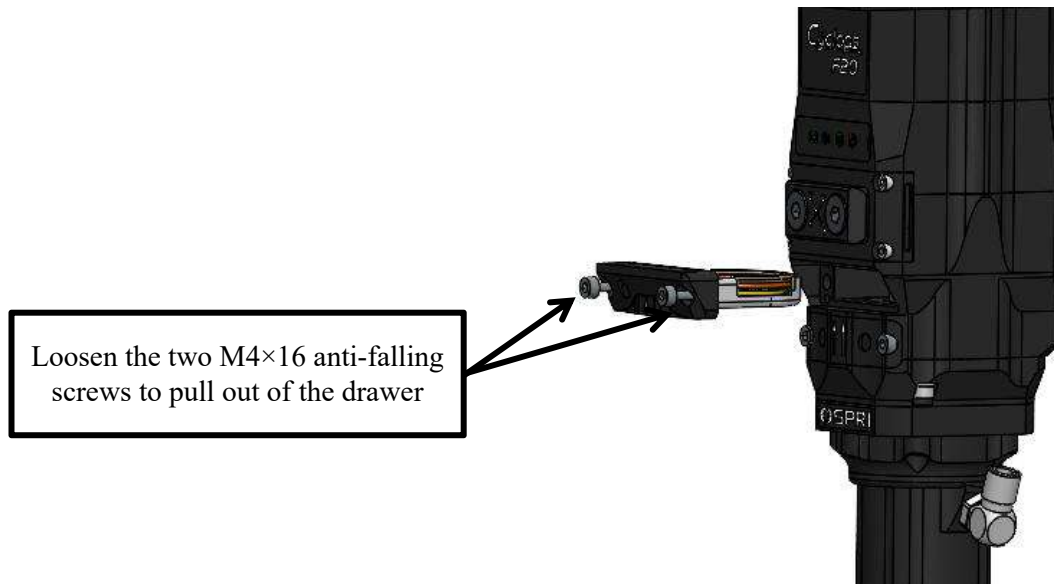


Figure 4.4

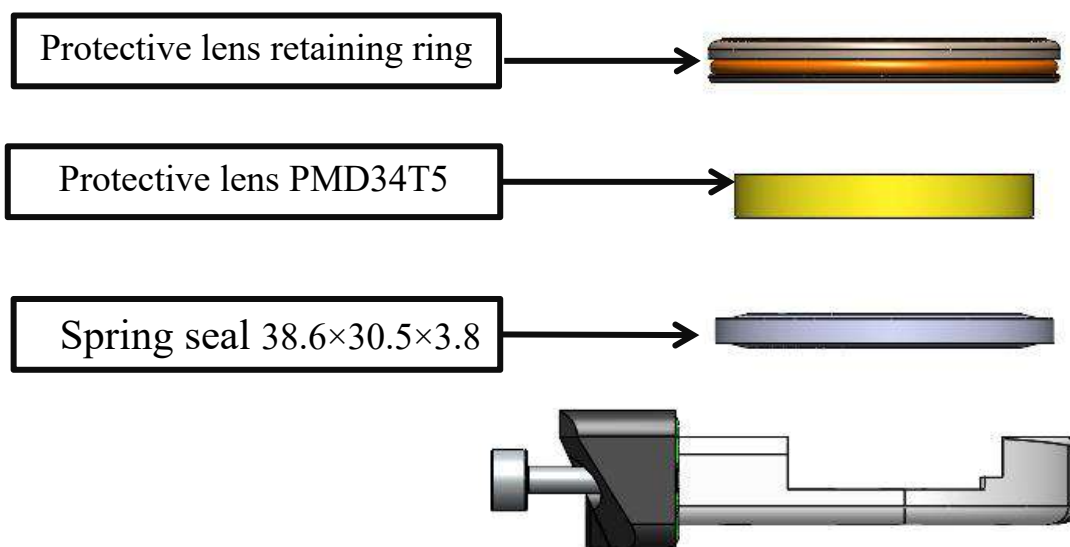


Figure 4.5

5.2 Maintenance and Replacement of Collimation Lens

5.2.1 Disassembly and Assembly of Collimation Lens

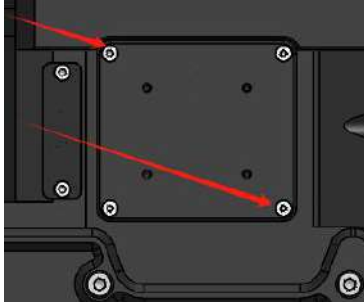


Figure 4.6

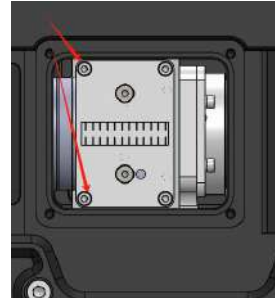


Figure 4.7

Remove the 4 M3X6 countersunk screws shown in Figure 4.6 above in order. After removing the cover plate, remove the 4 M2.5X6 bolts in Figure 4.7 above and pull out of the collimation lens drawer for maintenance. Pay attention to the direction of the collimation lens drawer during installation.

5.2.2 Cleaning of Collimation Lens



Figure 4.8

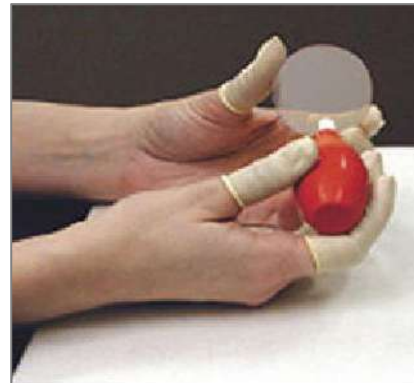


Figure 4.9

- ① Tools: Dust-free swab, isopropyl alcohol, and canned dry and purified compressed air.
- ② Spray isopropyl alcohol onto the dust-free swab.
- ③ Gently pinch the side edge of the lens with the left thumb and index finger, and hold the wiping swabs with right hand to gently wipe both sides of the lens in a single direction from bottom to top or from left to right, as shown in Figure 4.8.
- ④ After wiping, blow the lens surface again with canned dry and purified compressed air to ensure that the lens surface is free of any foreign matter, as shown in Figure 4.9.
- ⑤ The cleaned collimation lens must be installed into the base quickly and inserted into the cutting head.

5.3 Maintenance and Replacement of Focus Lens

5.3.1 Disassembly and Assembly of Focus Lens.

- ① As shown in Figure 5.0 below, loosen the 4 M3×12 anti-falling screws to pull out of the focus lens drawer; then take the focus lens out by using wrench.



Figure 5.1

5.3.2 Cleaning of Focus Lens.



Figure 5.1



Figure 5.2

- ① Tools: Dust-free swab, isopropyl alcohol, and canned dry and purified compressed air.
- ② Spray isopropyl alcohol onto the dust-free swab.
- ③ Gently pinch the side edge of the lens with the left thumb and index finger, and hold the wiping swabs with right hand to gently wipe both sides of the lens in a single direction from bottom to top or from left to right, as shown in Figure 5.1.
- ④ After wiping, blow the lens surface again with canned dry and purified compressed air to ensure that the lens surface is free of any foreign matter, as shown in Figure 5.2.
- ⑤ The cleaned focus lens must be installed into the base quickly and inserted into the cutting head.

5.4 Maintenance and Replacement of Cutting Protection Lens

When impurities or foreign objects adhere to the protective lens, they can absorb laser heat and cause damage to the lens. Therefore, it is necessary to clean the protective lens regularly, with a recommended cleaning cycle of once a week. Besides, the protective lens is a wearing part and should be replaced in time if damaged.

5.4.1 Disassembly of Protective Lens.

Loosen the two M4×10 anti-falling screws, hold the screws with both hands, slowly pull out the protective lens base, and move it to a clean and dust-free environment, as shown in Figure 5.3 below. The detailed diagram of replacing lens is shown in Figure 5.4.

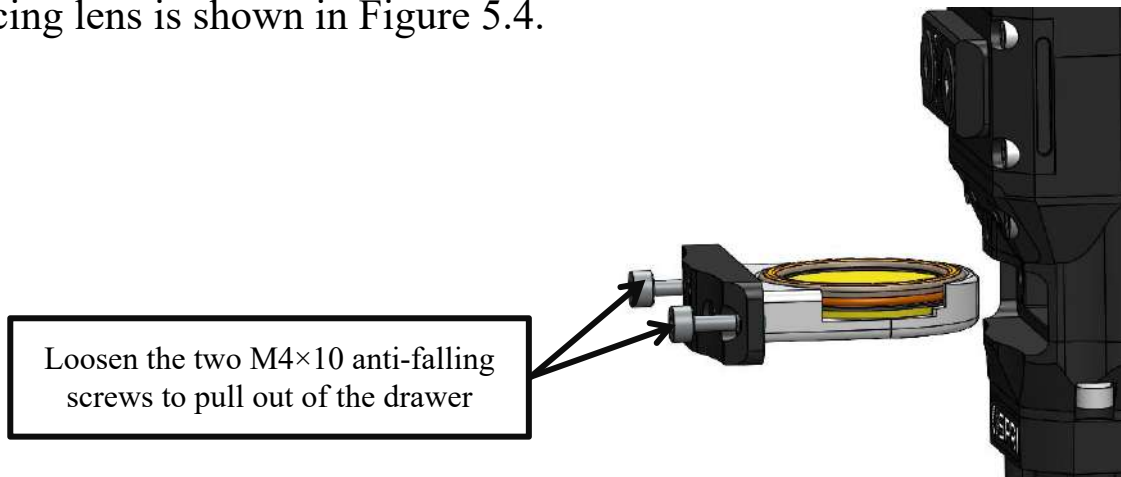


Figure 5.3

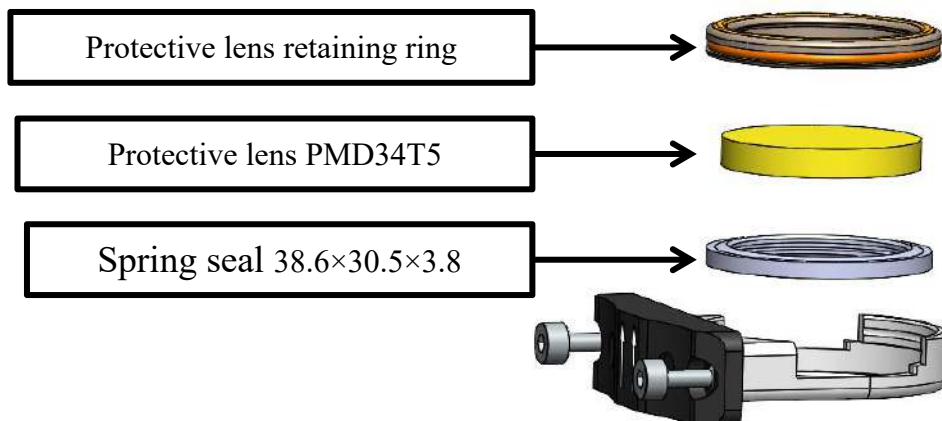


Figure 5.4

Assembly sequence is shown in the figure above.

5.4.2 Cleaning of Protective Lens



Figure 5.5

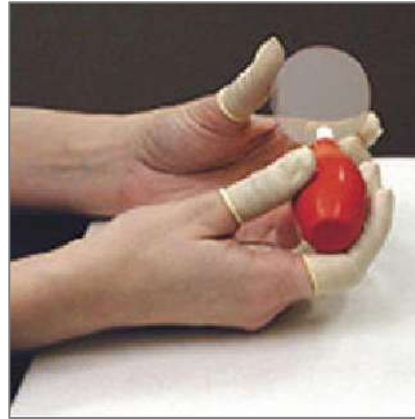


Figure 5.6

- ① Tools: Dust-free swab, isopropyl alcohol, and canned dry and purified compressed air.
- ② Spray isopropyl alcohol onto the dust-free swab.
- ③ Gently pinch the side edge of the lens with the left thumb and index finger, and hold the wiping swabs with right hand to gently wipe both sides of the lens in a single direction from bottom to top or from left to right, as shown in Figure 5.5.
- ④ After wiping, blow the lens surface again with canned dry and purified compressed air to ensure that the lens surface is free of any foreign matter, as shown in Figure 5.6.
- ⑤ The cleansed lens must be installed into the base quickly and inserted into the cutting head.

Note: When cleaning or replacing the protective lens, avoid contaminating it with oil from your hands or dust from the environment.

In principle, it is forbidden to disassemble the focus lens, collimation lens and cutting lens. If any lens is contaminated, make test using trial lens. If necessary, contact the Company's technicians.

5.5 Maintenance of Sensory Parts

The ceramic body is a wearable part and can be replaced after damage. When installing the ceramic body, align it with the two positioning pins on the main body. Otherwise, the ceramic body cannot be installed correctly in place, which may cause the failure of sensory parts. When tightening the ceramic body, use locking nut to secure it tightly. Inconsistent tightness of the locking nut will directly affect the operating parameters of the sensory parts.

The laser nozzle is the sensitive element of the sensory part and is connected to the main body through threading. It is a wearable part. After it is used for a period of time, remove the bonded slag. If the burnout is severe, replace it in a timely manner.

After assembling the ceramic body, tighten the locking nut so that the ceramic is evenly exposed by about 2-3mm.

Pay attention to the followings during use:

- ① Use dry and purified auxiliary gas for cutting. When the gas contains impurities such as water or oil, the working gap may undergo sudden changes, and may even cause sensor malfunction. It is recommended to use high-purity oxygen, and to also equip gas dryers, oil-water separators, etc.
- ② Clean the contaminated sensor. Use a clean, dry cotton cloth or similar material for cleaning. Do not use liquids to clean the cutting head or ceramic body. After cleaning, ensure proper connection and assembly.
- ③ The ceramic body can be replaced if damaged. After replacement, initialize the electrical system through a reset operation using an amplifier.
- ④ The shape and size of the cutting nozzle directly affect the characteristics of sensor. Therefore, it is necessary to use the specified cutting nozzle.

5.5.1 Replacement of Nozzles and Ceramic Body

- ① Remove the nozzle counterclockwise, as shown in Figure 6.0.
- ② Remove the ceramic clamp ring counterclockwise, as shown in Figure 6.0.
- ③ Remove the ceramic body vertically downward, as shown in Figure 6.0.

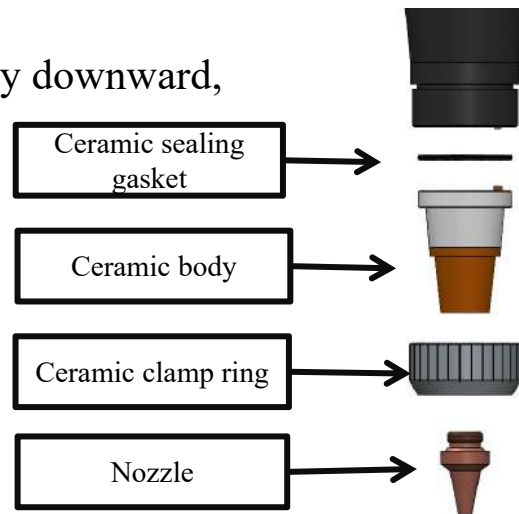


Figure 6.0

5.5.2 Cleaning of the Ceramic Ring.

- ① Take out the ceramic and clean it with anhydrous alcohol or isopropyl alcohol, as shown in Figure 6.1.
- ② Spray isopropyl alcohol onto the dust-free swab, remove the ceramic ring and clean it with the swab, as shown in Figure 6.2.
- ③ After wiping, blow the ceramic ring with filled dry and purified compressed air to clean it and ensure that the ceramic surface is clean, dry and free of moisture before installation, as shown in Figure 6.3.



Figure 6.1



Figure 6.2

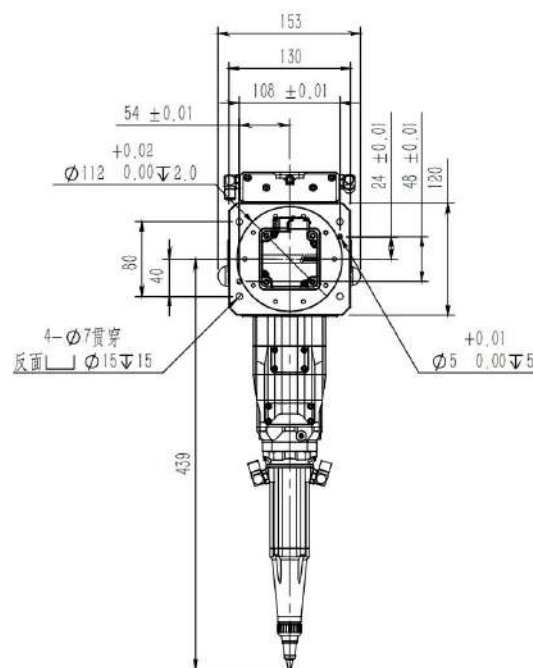
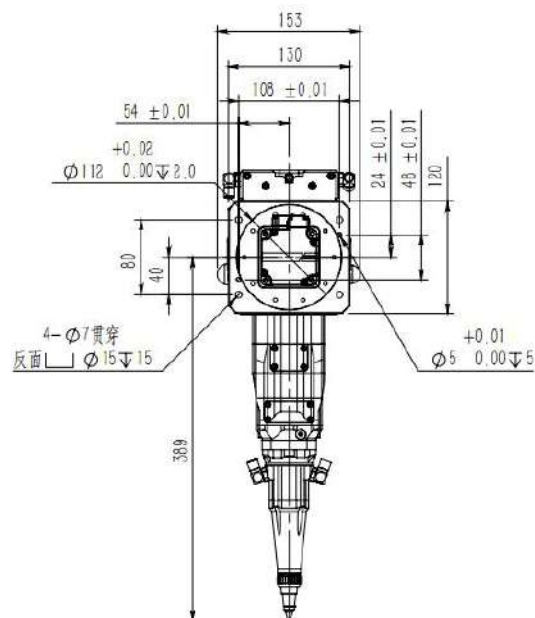


Figure 6.3

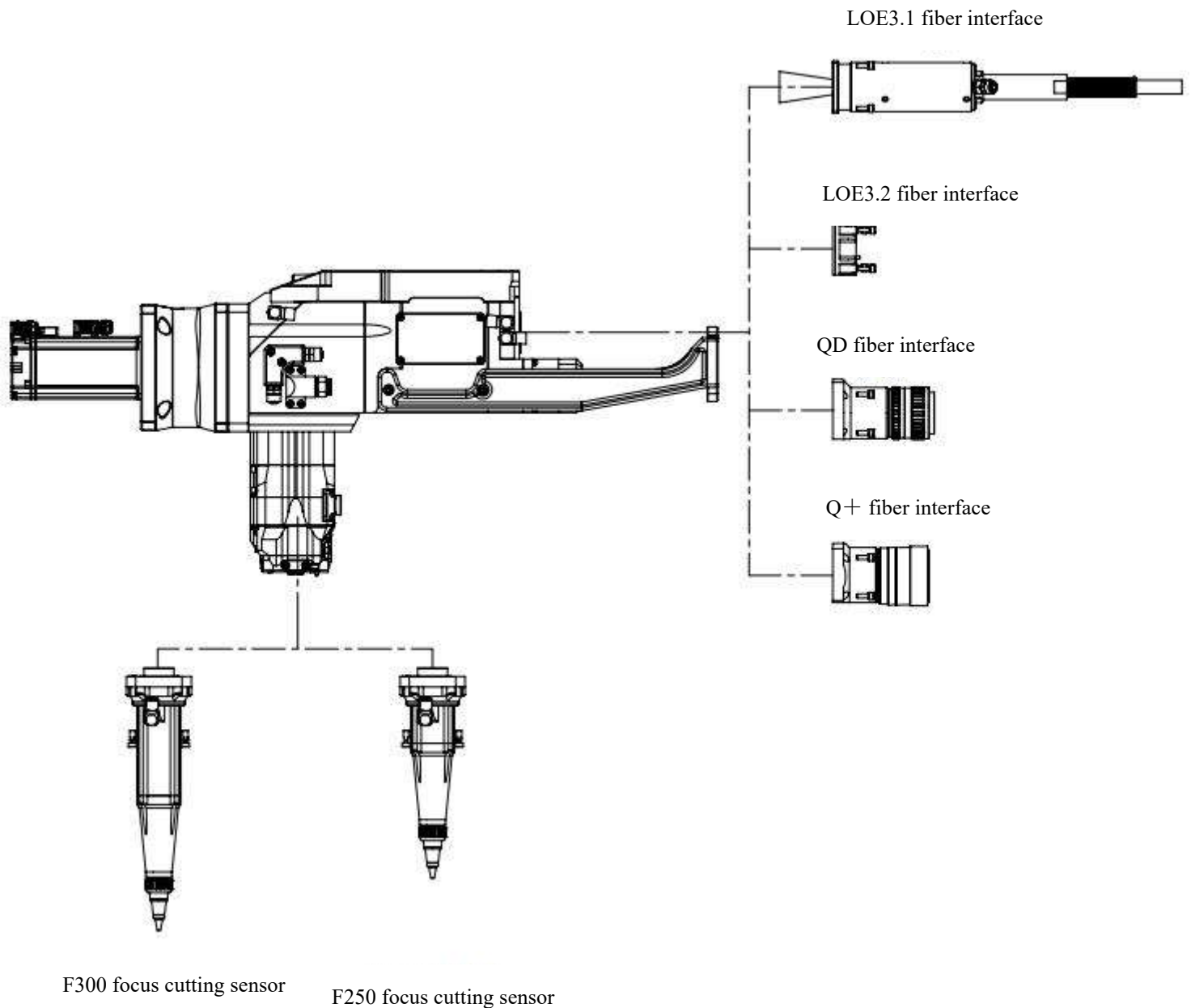
Note: Cleanliness of ceramic surface is directly related to the operating performance of the following system.

It is necessary to clean timely the dirt on the ceramic surface in order to ensure the working performance of the system.

1. Installation diagram of different cutting sensors

[illegible]

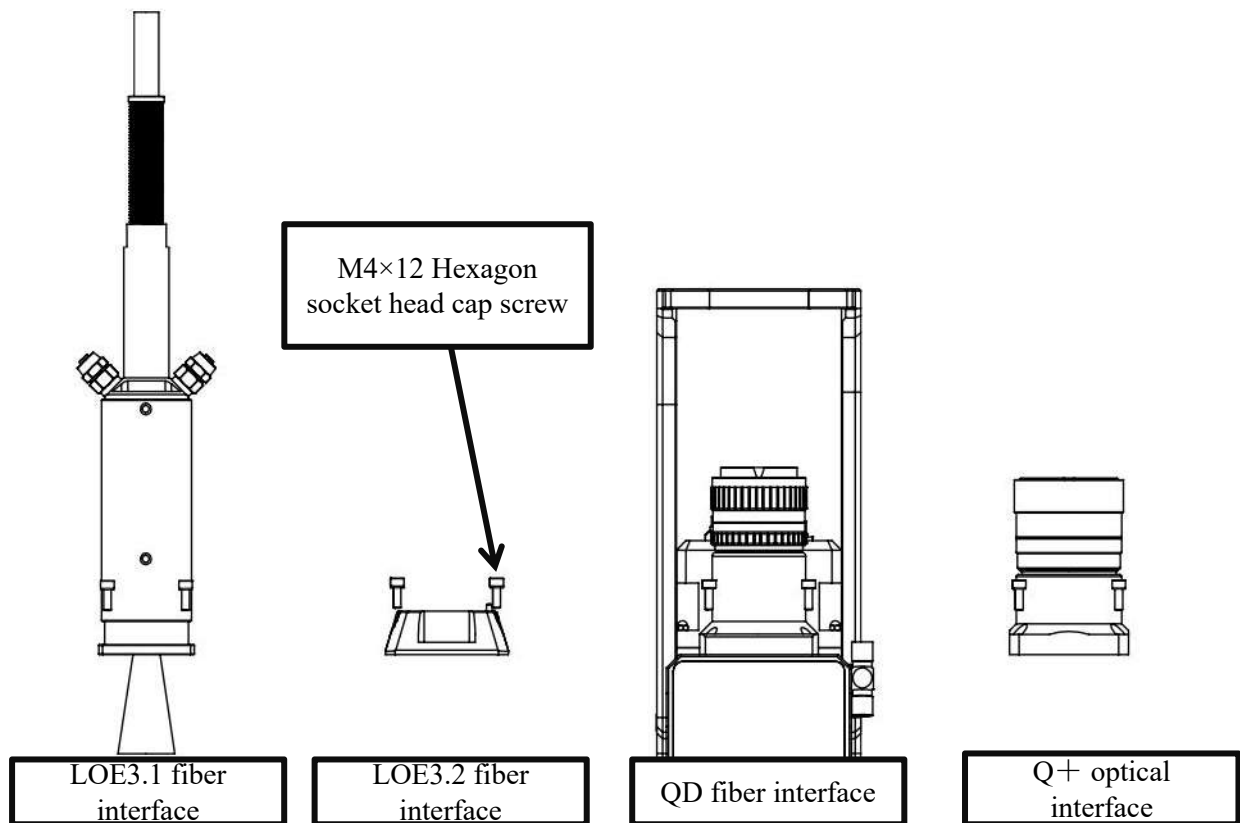
2. Introduction to Fiber Interface and Sensors with Different Focal Lengths



3. Replacement of Fiber Interface and Sensors with Different Focal Lengths

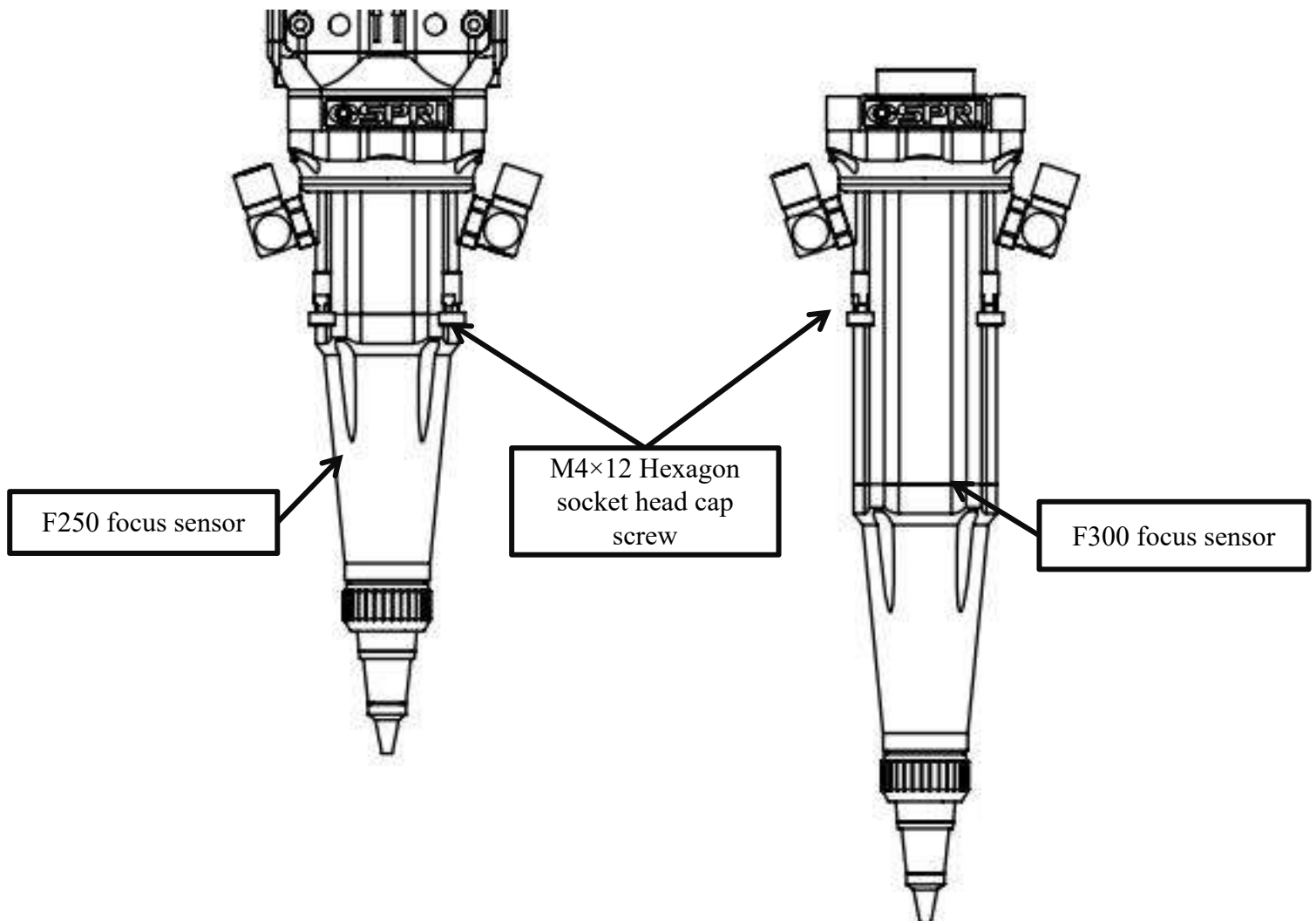
3.1 Replacement of Fiber Interface (The following uses QD as an example)

- ① Remove QD fiber interface: Move the cutting head to a dust-free environment, unscrew the 4-M4×12 Hexagon socket head cap screw and spring washer to remove the QD interface.
- ② Assemble optical fiber ports: Tighten the 4-M4x12 hex socket cylindrical head screws and spring washers, and secure the corresponding interfaces.



3.2 Replacement of Cutting Sensor (Taking the replacement of F250 focus to F300 focus as an example)

- ① Remove F250 focus sensor: Move the cutting head to a dust-proof environment and remove 4-M5 anti-collision screw to remove F250 focus sensor.
- ② Assemble F300 focus sensor: Lock 4-M5 anti-collision screw, and fasten and assemble F300 focus sensor.





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